Tensor-Train Decomposition for High-Dimensional Economic Models

Johannes Brumm Jakob Hußmann EEA-ESEM 2024

Karlsruhe Institute of Technology

1. [Introduction](#page-2-0)

2. [Method](#page-18-0)

3. [Economic Application](#page-70-0)

4. [Conclusion](#page-86-0)

[Introduction](#page-2-0)

Quantitative Macro Models

Quantitative Macro Models

1. Heterogeneous Agents:

overlapping generations, continuum of agents, discrete types.

Quantitative Macro Models

- 1. Heterogeneous Agents: overlapping generations, continuum of agents, discrete types.
- 2. Multiple Assets:

liquid-/illiquid assets, housing.

Quantitative Macro Models

- 1. Heterogeneous Agents: overlapping generations, continuum of agents, discrete types.
- 2. Multiple Assets:

liquid-/illiquid assets, housing.

3. Aggregate Risk:

realistically large shocks.

Quantitative Macro Models

- 1. Heterogeneous Agents: overlapping generations, continuum of agents, discrete types.
- 2. Multiple Assets: liquid-/illiquid assets, housing.
- 3. Aggregate Risk: realistically large shocks.

High-Accuracy Solutions

Quantitative Macro Models

- 1. Heterogeneous Agents: overlapping generations, continuum of agents, discrete types.
- 2. Multiple Assets: liquid-/illiquid assets, housing.
- 3. Aggregate Risk: realistically large shocks.

High-Accuracy Solutions

• Global Solution Techniques: when shocks are large.

Quantitative Macro Models

- 1. Heterogeneous Agents: overlapping generations, continuum of agents, discrete types.
- 2. Multiple Assets: liquid-/illiquid assets, housing.
- 3. Aggregate Risk: realistically large shocks.

High-Accuracy Solutions

- Global Solution Techniques: when shocks are large.
- Curse of Dimensionality: infeasible in high dimensions!

Related Literature

grid size grows exponentially in dimensions. Infeasible for *d >* 3.

grid size grows exponentially in dimensions. Infeasible for *d >* 3.

Advanced Methods

grid size grows exponentially in dimensions. Infeasible for *d >* 3.

Advanced Methods

1. Sparse Grids: Brumm and Scheidegger [\(2017\)](#page-91-0),Krueger and Kubler ([2006](#page-92-0)), ...

- reduce grid sizes, focus on important points
- good in medium dimensions
- grids still grow to an overwhelming size for *d >* 20

grid size grows exponentially in dimensions. Infeasible for *d >* 3.

Advanced Methods

- 1. Sparse Grids: Brumm and Scheidegger [\(2017\)](#page-91-0),Krueger and Kubler ([2006](#page-92-0)), ...
	- reduce grid sizes, focus on important points
	- good in medium dimensions
	- grids still grow to an overwhelming size for *d >* 20
- 2.**Neural Nets:** Azinovic et al. [\(2022\)](#page-91-1), Fernandez-Villaverde et al. ([2020](#page-91-2)), ...
	- can handle large problems *d >* 20
	- black-box optimization
	- convergence depends on hyper-parameters

grid size grows exponentially in dimensions. Infeasible for *d >* 3.

Advanced Methods

- 1.**Sparse Grids:** Brumm and Scheidegger [\(2017\)](#page-91-0), Krueger and Kubler ([2006](#page-92-0)), ...
	- reduce grid sizes, focus on important points
	- good in medium dimensions
	- grids still grow to an overwhelming size for *d >* 20
- 2.**Neural Nets:** Azinovic et al. [\(2022\)](#page-91-1), Fernandez-Villaverde et al. ([2020](#page-91-2)), ...
	- can handle large problems *d >* 20
	- black-box optimization
	- convergence depends on hyper-parameters

→ Still room for improvement!

Novel global solution technique based on the Tensor-Train Decomposition.

[Method](#page-18-0)

The Solution Technique in a Nutshell

fixed-point solution approach using non-linear solvers.

fixed-point solution approach using non-linear solvers.

2. Selection of Points:

Sample from the ergodic set (no curse of dimensionality!)

fixed-point solution approach using non-linear solvers.

2. Selection of Points:

Sample from the ergodic set (no curse of dimensionality!)

3. Policy Approximations:

High-dimensional off-grid interpolation (*→* high complexity!)

fixed-point solution approach using non-linear solvers.

2. Selection of Points:

Sample from the ergodic set (no curse of dimensionality!)

3. Policy Approximations:

High-dimensional off-grid interpolation (*→* high complexity!)

⇒ Tensor-Train Decomposition

$$
\hat{f}(\vec{x}) = \sum_{i_1=1}^m \ldots \sum_{i_d=1}^m A[i_1, ..., i_d] \cdot \left(\phi_{i_1}(x_1) \cdot \ldots \cdot \phi_{i_d}(x_d) \right)
$$

• Products of one-dimensional basis-functions *ϕ*

$$
\hat{f}(\vec{x}) = \sum_{i_1=1}^m \ldots \sum_{i_d=1}^m A[i_1, ..., i_d] \cdot \left(\phi_{i_1}(x_1) \cdots \phi_{i_d}(x_d) \right)
$$

- Products of one-dimensional basis-functions *ϕ*
- *m* basis-functions in each dimension 1*, . . . , d*

$$
\hat{f}(\vec{x}) = \sum_{i_1=1}^m \cdots \sum_{i_d=1}^m A[i_1, ..., i_d] \cdot \underbrace{(\phi_{i_1}(x_1) \cdots \cdots \phi_{i_d}(x_d))}_{\text{basis function } i_1} \underbrace{\phi_{i_d}(x_d)}_{\text{basis function } i_1}
$$

- Products of one-dimensional basis-functions *ϕ*
- *m* basis-functions in each dimension 1*, . . . , d*
- \cdot Combination i_1, \ldots, i_d weighted with $A[i_1, \ldots, i_d]$

$$
\hat{f}(\vec{x}) = \sum_{i_1=1}^m \cdots \sum_{i_d=1}^m \underbrace{A[i_1, ..., i_d]}_{\text{tensor of weights}} \cdot \underbrace{(\phi_{i_1}(x_1) \cdots \cdots \phi_{i_d}(x_d))}_{\text{basis function } i_1} \newline \text{basis function } i_1
$$

- Products of one-dimensional basis-functions *ϕ*
- *m* basis-functions in each dimension 1*, . . . , d*
- \cdot Combination i_1, \ldots, i_d weighted with $A[i_1, \ldots, i_d]$
- Sum up over all permutations, Richter et al. [\(2023\)](#page-92-1)

$$
\hat{f}(\vec{x}) = \sum_{\substack{i_1=1 \text{ sum over all} \\ \text{sum over all} \\ \text{dimensions 1, ..., } d}}^{m} \underbrace{A[i_1, ..., i_d]}_{\text{tensor of} \atop \text{weights}} \cdot \underbrace{(\phi_{i_1}(x_1) \cdots \cdots \phi_{i_d}(x_d))}_{\text{basis function } i_1}
$$
\n
$$
\dots \cdot \underbrace{\phi_{i_d}(x_d)}_{\text{basis function } i_1}
$$
\n
$$
\dots \cdot \underbrace{\phi_{i_d}(x_d)}_{\text{basis function } i_1}
$$

- Products of one-dimensional basis-functions *ϕ*
- *m* basis-functions in each dimension 1*, . . . , d*
- \cdot Combination i_1, \ldots, i_d weighted with $A[i_1, \ldots, i_d]$
- Sum up over all permutations, Richter et al. [\(2023\)](#page-92-1)

\rightarrow A is an order-d tensor with m^dentries!

Handling the exponential size of *A*

1. Exploit Structure:

Symmetry, smoothness, linearity (*→* latent low rank!)

Handling the exponential size of *A*

1. Exploit Structure:

Symmetry, smoothness, linearity (*→* latent low rank!)

2. Decomposition:

Decompose *A* into a sequence of smaller objects with lower rank.

Handling the exponential size of *A*

1. Exploit Structure:

Symmetry, smoothness, linearity (*→* latent low rank!)

2. Decomposition:

Decompose *A* into a sequence of smaller objects with lower rank.

3. Oseledets([2011\)](#page-92-2):

Decompose order-*d* tensor of size *m^d* into a sequence of *d* order-3 tensors with size *mr*² .

→ Tensor-Train Decomposition

Tensor-Train Decomposition – 2D Special Case

Tensor-Train Decomposition – 2D Special Case

• Approximate (*m × m*)-matrix *A*

$$
\boxed{A} = \boxed{\boxed{A} \boxed{\boxed{m \times m}}
$$
Tensor-Train Decomposition – 2D Special Case

- Approximate (*m × m*)-matrix *A*
- \cdot outer-product of $(m \times r)$ -matrices U_1, U_2

Tensor-Train Decomposition – 2D Special Case

- Approximate (*m × m*)-matrix *A*
- \cdot outer-product of $(m \times r)$ -matrices U_1, U_2

$$
\boxed{A} = \boxed{U_1} \circ \boxed{U_2}
$$
\n
$$
\boxed{(m \times m)} \quad (\text{mx } r)
$$

Tensor-Train Decomposition – 2D Special Case

- Approximate (*m × m*)-matrix *A*
- \cdot outer-product of $(m \times r)$ -matrices U_1, U_2
- error *ε* low if *A* has low rank

(*m × r*) *◦* (*r × m*)

$$
\overbrace{(m \times r)}^{U_1} \circ \overbrace{(r \times m)}^{U_2}
$$

Tensor Completion

$(m \times r)$ $(r \times m)$

$$
\overbrace{(m \times r)}^{U_1} \circ (r \times m \times r) \circ \overbrace{(r \times m)}^{U_3}
$$

$$
\overbrace{(m \times r)}^{U_1} \circ \overbrace{(r \times m \times r)}^{U_2} \circ \overbrace{(r \times m)}^{U_3}
$$

$$
\overbrace{(m \times r)}^{U_1} \circ \overbrace{(r \times m \times \mathbf{K})}^{U_2} \circ \overbrace{(\mathbf{K} \times m)}^{U_3}
$$

$$
\overbrace{(m\times \mathbf{K})}^{U_1} \circ \underbrace{\overbrace{(r\times m\times \mathbf{K})}^{U_2} \circ \overbrace{(\mathbf{K}\times m)}^{U_3}}_{\mathbf{K}\times m\times m)}
$$

Tensor Completion

same principle for *d >* 3!

$$
A \quad \approx \quad U_1 \quad \circ \quad U_2 \quad \circ \ldots \circ \quad U_{d-1} \quad \circ \quad U_d
$$

General Case

Scaling Example

General Case

Scaling Example

| d | $\#\mathsf{A}$ | › `#U |
|-----|-----------------|-------|
| V | 100 | 100 |
| 5 | 10 ⁵ | 850 |
| 10 | 10^{10} | 2100 |
| 100 | 10^{100} | 24600 |

Table 1: Object size for different *d* with $m = 10$ and $r = 5$.

Approximation

Approximation

 \cdot Replace A by its decomposition U_1, \ldots, U_d

Approximation

- \cdot Replace A by its decomposition U_1, \ldots, U_d
- Sequential contractions from end to end

Approximation

- \cdot Replace A by its decomposition U_1, \ldots, U_d
- Sequential contractions from end to end

$$
\hat{f}(x) = U_1 \circ \ldots \circ \left(\left(U_{d-1} \circ (U_d \circ \phi(x_d)) \circ \phi(x_{d-1}) \right) \circ \ldots \circ \phi(x_1) \right)
$$

Approximation

- \cdot Replace A by its decomposition U_1, \ldots, U_d
- Sequential contractions from end to end

$$
\hat{f}(x) = U_1 \circ \ldots \circ \left(\left(U_{d-1} \circ (U_d \circ \phi(x_d)) \circ \phi(x_{d-1}) \right) \circ \ldots \circ \phi(x_1) \right)
$$

Computing the Decomposition

Approximation

- \cdot Replace A by its decomposition U_1, \ldots, U_d
- Sequential contractions from end to end

$$
\hat{f}(x) = U_1 \circ \ldots \circ \left(\left(U_{d-1} \circ (U_d \circ \phi(x_d)) \circ \phi(x_{d-1}) \right) \circ \ldots \circ \phi(x_1) \right)
$$

Computing the Decomposition

• Non-linear approximation problem

Approximation

- \cdot Replace A by its decomposition U_1, \ldots, U_d
- Sequential contractions from end to end

$$
\hat{f}(x) = U_1 \circ \ldots \circ \left(\left(U_{d-1} \circ (U_d \circ \phi(x_d)) \circ \phi(x_{d-1}) \right) \circ \ldots \circ \phi(x_1) \right)
$$

Computing the Decomposition

- Non-linear approximation problem
- Decomposed in a sequence of linear problems, Holtz et al. [\(2012](#page-91-0))

[Economic Application](#page-70-0)

Economic Application

Model Setup
Model Setup

• Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.

Model Setup

- Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.
- NK-Production: with Rotemberg price adjustment costs and union bargaining.

Model Setup

- Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.
- \cdot NK-Production: with Rotemberg price adjustment costs and union bargaining.
- Government: faces large spending shocks, 20% of GPD every decade.

Model Setup

- Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.
- \cdot NK-Production: with Rotemberg price adjustment costs and union bargaining.
- Government: faces large spending shocks, 20% of GPD every decade.
- Aggregate Risk: persistent large shocks.

Model Setup

- Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.
- NK-Production: with Rotemberg price adjustment costs and union bargaining.
- Government: faces large spending shocks, 20% of GPD every decade.
- Aggregate Risk: persistent large shocks.

Research Questions

Model Setup

- Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.
- \cdot NK-Production: with Rotemberg price adjustment costs and union bargaining.
- Government: faces large spending shocks, 20% of GPD every decade.
- Aggregate Risk: persistent large shocks.

Research Questions

1. Impact of large shocks on debt, inflation and taxation?

Model Setup

- Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.
- \cdot NK-Production: with Rotemberg price adjustment costs and union bargaining.
- Government: faces large spending shocks, 20% of GPD every decade.
- Aggregate Risk: persistent large shocks.

Research Questions

- 1. Impact of large shocks on debt, inflation and taxation?
- 2. How are expenses financed depending on the policy?

Model Setup

- Large Scale OLG: with yearly calibration, portfolio choice, endogenous labor.
- \cdot NK-Production: with Rotemberg price adjustment costs and union bargaining.
- Government: faces large spending shocks, 20% of GPD every decade.
- Aggregate Risk: persistent large shocks.

Research Questions

- 1. Impact of large shocks on debt, inflation and taxation?
- 2. How are expenses financed depending on the policy?
- 3. Intergenerational impact of different policy?

Computational Problem

- 60 Generations
- two types of assets
- three aggregate shocks
- five policy parameters

- 60 Generations
- two types of assets
- three aggregate shocks
- five policy parameters

Policy Functions

- 120 individual policies
- 4 aggregate policies

- 60 Generations
- two types of assets
- three aggregate shocks
- five policy parameters

Policy Functions

- 120 individual policies
- 4 aggregate policies

→ Computationally very challenging!

- 60 Generations
- two types of assets
- three aggregate shocks
- five policy parameters

Policy Functions

- 120 individual policies
- 4 aggregate policies

- *→* Computationally very challenging!
- *→* The proposed method solves the problem in 2h on a PC!

Results

- Average relative error in consumption 0*.*014%
- Average market clearing error 0*.*036%
- Q99 consumption error *<* 0*.*08%

[Conclusion](#page-86-0)

Conclusion

1. We present a new global solution technique for high-dimensional economic problems.

- 1. We present a new global solution technique for high-dimensional economic problems.
- 2. We exploit the Tensor-Train Decomposition for efficient approximations.
- 1. We present a new global solution technique for high-dimensional economic problems.
- 2. We exploit the Tensor-Train Decomposition for efficient approximations.
- 3. We solve a high-dimensional economic application with high accuracy, at low computational cost.

[References](#page-91-0)

Azinovic, M., Gaegauf, L., & Scheidegger, S. (2022).Deep equilibrium nets. *International Economic Review*, *63*(4), 1471–1525. Brumm, J., & Scheidegger, S. (2017).Using adaptive sparse grids to solve high-dimensional dynamic models. *Econometrica*, *85*(5), 1575–1612. Fernandez-Villaverde, J., Nuno, G., Sorg-Langhans, G., & Vogler, M. (2020).Solving high-dimensional dynamic programming problems using deep learning. *Working Paper*. Holtz, S., Rohwedder, T., & Schneider, R. (2012).The alternating linear scheme for tensor

optimization in the tensor train format. *SIAM Journal on Scientific Computing*, *34*(2), A683–A713.

Krueger, D., & Kubler, F. (2006).Pareto-improving social security reform when financial markets are incomplete!? *American Economic Review*, *96*(3), 737–755. Oseledets, I. V. (2011).Tensor-train decomposition. *SIAM Journal on Scientific Computing*, *33*(5), 2295–2317. Richter, L., Sallandt, L., & Nüsken, N. (2023). From continuous-time formulations to discretization schemes: Tensor trains and robust regression for bsdes and parabolic pdes.