Identifying Dynamic LATEs with a Static Instrument

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Motivation

- How can we identify dynamic effects with a time-invariant binary IV?
- Examples:
 - Dynamic effects of training programs. Schochet et al. (2008), Alzúa et al. (2016), Hirshleifer et al. (2016), Das (2021), and others.
 - Effects of having children on parents' labor supply. Bronars and Grogger (1994), Angelov and Karimi (2012), Silles (2015), Lundborg et al. (2017), and others.
- Main challenge: we can have individuals starting treatment at different time periods ("dynamic compliance").

- Common approach: period by period comparisons.
- <u>Problem</u>: individuals who are not offered training in the first period but that are trained afterward "contaminate" these estimates.
- \Rightarrow Negative weights for some causal effects in the usual estimands.
 - Estimands may be negative even when the treatment makes everyone better off.

- Decomposition results for the usual estimands (period by period comparisons).
 - Understand when there is contamination and which groups drive it.
- Point identification of dynamic effects for first-period compliers.
 - Achieved with some types of homogeneity assumptions on causal effects.
 - No additional source of exogenous variation is required.
- Partial identification when treatment effects are bounded.
 - Bounds valid without any homogeneity on causal effects.
 - Tighter bounds as a middle ground.

Two-Period Setting

Treatment and Lottery

- For example, consider a two-period evaluation of a training program.
 - ► See paper for the *T*-period setting.
- A lottery determines who gets a training offer in the first period.
- Z_i is the lottery outcome and $D_{i,t}$ indicates whether *i* is treated at $t \in \{1,2\}$.
- We assume that treatment is irreversible.

Assumption 1

 $D_{i,1}=1 \implies D_{i,2}=1.$

Potential Outcomes

- $Y_{i,t}(0)$ if i is not treated at t.
- $Y_{i,t}(1,\tau)$ if *i* started to be treated τ periods before *t*.

• At $t = 1$:	$\blacktriangleright \underline{\text{At } t = 2:}$
0: not treated at $t = 1$.	0: not treated at $t = 2$.
•••••••••••••••	(1,0): treated at $t=2$.
(1,0): treated at $t = 1$.	(1,1): treated at $t = 1$.

- Exclusion restriction: the lottery does not affect potential outcomes directly.
- $Y_{i,t}$ is the observable outcome.

Latent Groups

- Potential treatment statuses for observation *i* at *t* are denoted by $D_{i,t}(z)$, $z \in \{0,1\}$.
- We define the four usual IV latent types by period.

$D_{i,t}(0)=1$	AT _t	F _t
$D_{i,t}(0)=0$	C _t	NT _t

$$D_{i,t}(1) = 1$$
 $D_{i,t}(1) = 0$

- We say we have "dynamic compliance" if latent groups may change over time.
 - Example: (C_1, AT_2) is someone who is only treated at t = 1 if received $Z_i = 1$, but who will be treated at t = 2 regardless of Z_i .

• Treatment effects of interest compare treated and untreated potential outcomes:

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\Delta_t^{\tau}(g) \coloneqq \mathbb{E}\left[Y_{i,t}(1,\tau) - Y_{i,t}(0)|g
ight],
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where g is a history of IV types.

- We focus on:
 - $\Delta_1^0(C_1)$: effect in the first period for C_1 units.
 - $\Delta_2^1(C_1)$: effect at t = 2 of being treated in the first period for C_1 units.
- Focus on the dynamic effects over time for a fixed population (compliers from t = 1).

Basic Assumptions

• As a basic requirement, we assume that Z_i satisfies the following.

Assumption 2

- **(**) The instrument is excluded from potential outcomes given time period and treatment length.
- 2 Potential outcomes and potential treatment statuses are drawn independently of Z_i .

$$I FS_1 \neq 0.$$

- Notes:
 - For our solutions, we only need relevance of the instrument at t = 1;
 - 2 Also, we only need no defiers at t = 1.

Period by Period Estimators

• Reduced form and first stage estimands are

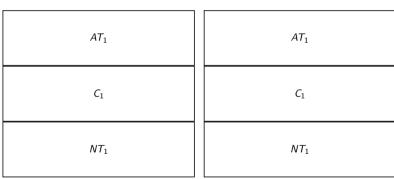
$$\begin{aligned} \mathsf{RF}_t &\coloneqq \mathbb{E}\left[\mathsf{Y}_{i,t} | Z_i = 1\right] - \mathbb{E}\left[\mathsf{Y}_{i,t} | Z_i = 0\right], \\ \mathsf{FS}_t &\coloneqq \mathbb{E}\left[\mathsf{D}_{i,t} | Z_i = 1\right] - \mathbb{E}\left[\mathsf{D}_{i,t} | Z_i = 0\right]. \end{aligned}$$

• Moreover,

IV estimand at
$$t \coloneqq \frac{RF_t}{FS_t}$$
.

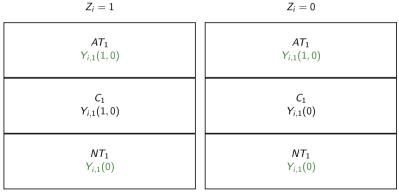
- $\Delta_1^0(C_1)$ is identified by RF_1/FS_1 (Imbens and Angrist 1994).
 - At t = 1 we don't have dynamic compliance problems.

 $Z_i = 1$



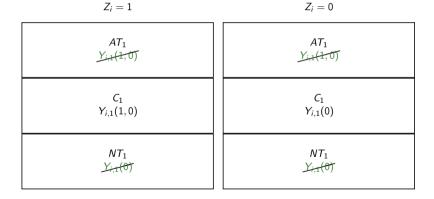
 $Z_i = 0$

- $\Delta_1^0(C_1)$ is identified by RF_1/FS_1 (Imbens and Angrist 1994).
 - At t = 1 we don't have dynamic compliance problems.



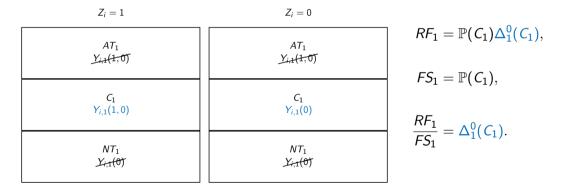
 $Z_i = 0$

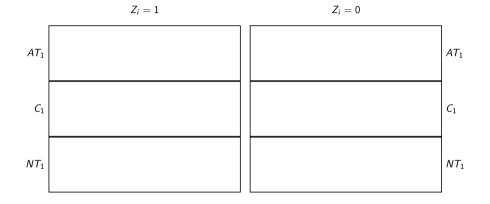
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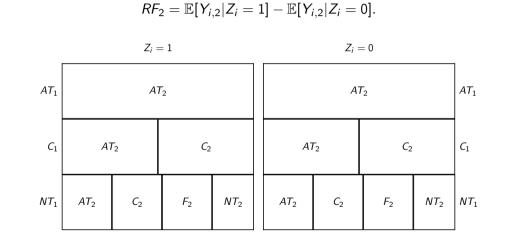
• $\Delta_1^0(C_1)$ is identified by RF_1/FS_1 (Imbens and Angrist 1994).

• At t = 1 we don't have dynamic compliance problems.



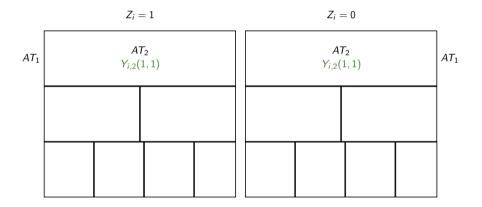


	$Z_i = 1$				$Z_i = 0$				
AT_1	AT ₂	<i>C</i> ₂	F ₂	NT ₂	AT ₂	С2	F ₂	NT ₂	AT_1
<i>C</i> ₁	AT ₂	<i>C</i> ₂	F ₂	NT ₂	AT ₂	<i>C</i> ₂	F ₂	NT ₂	С1
NT_1	AT ₂	<i>C</i> ₂	F ₂	NT ₂	AT ₂	<i>C</i> ₂	F ₂	NT ₂	AT_1



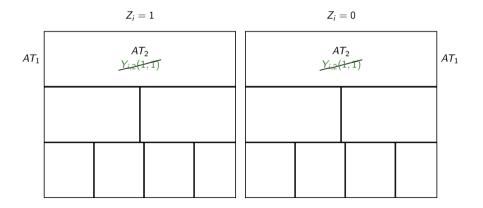
 $Y_{i,2}(0)$: not treated at t = 2 $Y_{i,2}(1,1)$: treated at t = 1 $Y_{i,2}(1,0)$: treated at t = 2

$$RF_2 = \mathbb{E}[Y_{i,2}|Z_i = 1] - \mathbb{E}[Y_{i,2}|Z_i = 0].$$



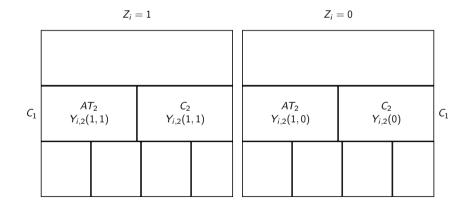
 $\begin{array}{l} Y_{i,2}(0): \text{ not treated at } t=2\\ Y_{i,2}(1,1): \text{ treated at } t=1\\ Y_{i,2}(1,0): \text{ treated at } t=2 \end{array}$

$$\mathsf{R}\mathsf{F}_2 = \mathbb{P}(\mathsf{A}\mathsf{T}_2) \cdot \mathsf{0} + \dots$$



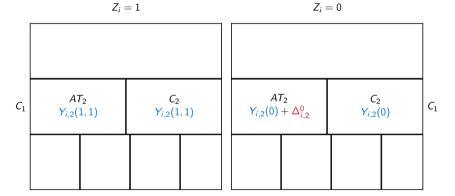
 $Y_{i,2}(0)$: not treated at t = 2 $Y_{i,2}(1,1)$: treated at t = 1 $Y_{i,2}(1,0)$: treated at t = 2

$$RF_2 = \mathbb{P}(AT_2) \cdot 0 + \dots$$

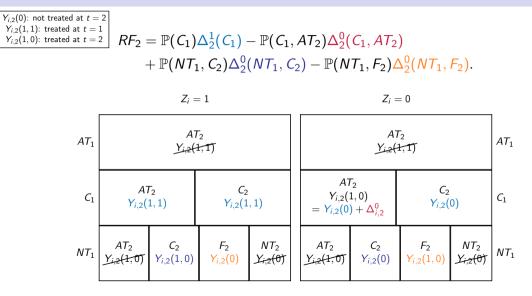


 $Y_{i,2}(0)$: not treated at t = 2 $Y_{i,2}(1,1)$: treated at t = 1 $Y_{i,2}(1,0)$: treated at t = 2

$$RF_2 = \mathbb{P}(C_1)\Delta_2^1(C_1) - \mathbb{P}(C_1, AT_2)\Delta_2^0(C_1, AT_2) + \dots$$



• **Problem**: potential outcomes of (C_1, AT_2) for $Z_i = 1$ and $Z_i = 0$ are not comparable, even though this group is treated at t = 2 regardless of Z_i .



$$\Delta_2^0$$
: effect at $t = 2$, treated at $t = 2$

 Δ_2^1 : effect at t=2, treated at t=1

$$\begin{aligned} \mathsf{R}\mathsf{F}_2 &= \mathbb{P}(\mathsf{C}_1)\Delta_2^1(\mathsf{C}_1) - \mathbb{P}(\mathsf{C}_1,\mathsf{A}\mathsf{T}_2)\Delta_2^0(\mathsf{C}_1,\mathsf{A}\mathsf{T}_2) \\ &+ \mathbb{P}(\mathsf{N}\mathsf{T}_1,\mathsf{C}_2)\Delta_2^0(\mathsf{N}\mathsf{T}_1,\mathsf{C}_2) - \mathbb{P}(\mathsf{N}\mathsf{T}_1,\mathsf{F}_2)\Delta_2^0(\mathsf{N}\mathsf{T}_1,\mathsf{F}_2) \end{aligned}$$

and

$$FS_2 = \mathbb{P}(C_1) - \mathbb{P}(C_1, AT_2) + \mathbb{P}(NT_1, C_2) - \mathbb{P}(NT_1, F_2).$$

Notes:

- Weights in the IV estimand sum to one; but some may be negative.
- If $FS_2 < FS_1$, then there must be negative weights.
- ▶ No defiance in all periods does not eliminate all negative weights:

 $RF_{2} = \mathbb{P}(C_{1})\Delta_{2}^{1}(C_{1}) - \mathbb{P}(C_{1}, AT_{2})\Delta_{2}^{0}(C_{1}, AT_{2}) + \mathbb{P}(NT_{1}, C_{2})\Delta_{2}^{0}(NT_{1}, C_{2}) - \mathbb{P}(NT_{1}, E_{2})\Delta_{2}^{0}(NT_{1}, F_{2}).$

When Does the IV Estimand Work?

Compliance is static

 Δ_2^0 : effect at t=2, treated at t=2 Δ_2^1 : effect at t=2, treated at t=1

• Compliance is static $\Rightarrow \mathbb{P}(C_1, AT_2) = \mathbb{P}(NT_1, C_2) = \mathbb{P}(NT_1, F_2) = 0.$

$$RF_2 = \mathbb{P}(C_1)\Delta_2^1(C_1) - \mathbb{P}(C_1, AT_2)\Delta_2^0(C_1, AT_2)$$
$$+ \mathbb{P}(NT_1, C_2)\Delta_2^0(NT_1, C_2) - \mathbb{P}(NT_1, E_2)\Delta_2^0(NT_1, F_2),$$

$$FS_2 = \mathbb{P}(C_1) - \mathbb{P}(C_1, AT_2) + \mathbb{P}(NT_1, C_2) - \mathbb{P}(NT_1, F_2).$$

When Does the IV Estimand Work?

Treatment length homogeneity

Assumption 3

For any latent group $g \in \{(C_1, AT_2), (NT_1, C_2), (NT_1, F_2)\}$ such that $\mathbb{P}(g) > 0$, $\Delta_2^1(C_1) = \Delta_2^0(g)$.

- Treatment effect may vary with calendar time, but does not depend on length of exposure to the treatment.
 - Also needs homogeneity assumptions wrt latent groups.

$$RF_2 = \left[\mathbb{P}(C_1) - \mathbb{P}(C_1, AT_2) + \mathbb{P}(NT_1, C_2) - \mathbb{P}(NT_1, F_2) \right] \Delta_2^1(C_1)$$

$$FS_2 = \left[\mathbb{P}(C_1) - \mathbb{P}(C_1, AT_2) + \mathbb{P}(NT_1, C_2) - \mathbb{P}(NT_1, F_2) \right]$$

Point Identification Under Alternative Assumptions

Calendar Time Homogeneity

 Δ_2^0 : effect at t = 2, treated at t = 2 Δ_2^1 : effect at t = 2, treated at t = 1

Assumption 4

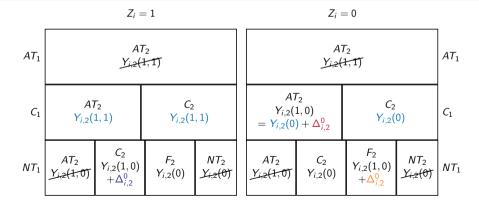
For any latent group $g \in \{(C_1, AT_2), (NT_1, C_2), (NT_1, F_2)\}$ such that $\mathbb{P}(g) > 0$, $\Delta_1^0(C_1) = \Delta_2^0(g)$.

- Treatment effect can vary with length of exposure to treatment (but does not depend on calendar time).
 - More reasonable than previous assumptions if we consider a time range in which economy is stable.
 - Also need homogeneity assumptions wrt latent groups.

Identification Under Calendar Time Homogeneity

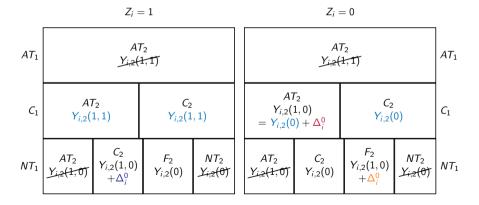
Assumption 4

For any latent group $g \in \{(C_1, AT_2), (NT_1, C_2), (NT_1, F_2)\}$ such that $\mathbb{P}(g) > 0$, $\Delta_1^0(C_1) = \Delta_2^0(g)$.

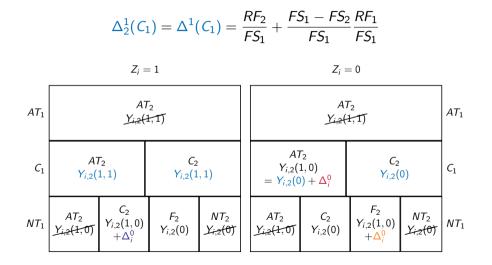


Identification Under Calendar Time Homogeneity

- $\Delta^0(C_1)$ is identified by the first-period IV estimand.
- Use it to correct the contamination term.



Identification Under Calendar Time Homogeneity



- <u>IV estimand</u>: calendar time heterogeneity but no time-since-treatment heterogeneity.
- Correction: calendar time homogeneity but unrestricted time-since-treatment heterogeneity.
- Both assume homogeneous effects for the other groups or that they do not exist (or a combination in between).
- Our correction only requires relevance in the first period.

• We can define a just-identified linear IV model in which the solution of the moment condition is the corrected IV estimand.

Estimate

$$Y_{i,t} = \gamma_1 1(t=1) + \gamma_2 1(t=2) + eta_1 (D_{i,t} - D_{i,t-1}) + eta_2 1(2 \le t) (D_{i,t-1} - D_{i,t-2}) + arepsilon_{i,t-1}$$

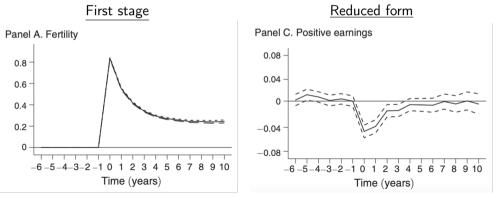
treating the time dummies as exogenous and using $1(t = 1)Z_i$ and $1(t = 2)Z_i$ as instruments for the endogenous variables.

• Estimation using standard GMM or two-stage least squares software gives valid inference.

Empirical Illustration

Lundborg et al. 2017 "Can Women Have Children and a Career? IV Evidence from IVF Treatments"

- $D_{i,t}$: fertility;
- Z_i: in vitro fertilization (IVF) treatment success;
- $Y_{i,t}$: labor force participation.

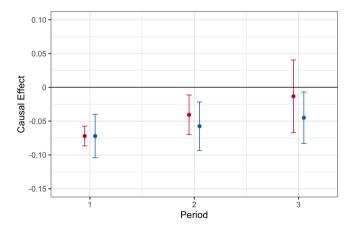




- Challenge: we don't have access to the microdata.
- Construct a dataset that matches the FS and the RF for all periods.
- Limitation 1: we cannot get the exact trajectories of $Y_{i,t}$ for each observation.
 - Trajectory does not affect our point estimates;
 - Very minor differences on se's; we use worst case over 1000 possible datasets.
- Limitation 2: we don't have information on $\mathbb{E}[Y_{i,t}|Z_i=0]$.
 - se's are maximized when $\mathbb{E}[Y_{i,t}|Z_i = 0] = 0.5$;
 - We use $\mathbb{E}[Y_{i,t}|Z_i = 0] = 0.8$ as a conservative estimate.
- Limitation 3: we don't have information on covariates.
 - se's for our correction are higher than they would be if we had covariates.

Lundborg et al. 2017 "Can Women Have Children and a Career? IV Evidence from IVF Treatments"

• Per-period vs Corrected IV.



• Under Assumptions 1 and 2 only,

$$\begin{aligned} \mathsf{FS}_1\Delta_2^1(\mathcal{C}_1) &= \mathsf{RF}_2 - \mathbb{P}(\mathsf{NT}_1, \mathcal{C}_2)\Delta_2^0(\mathsf{NT}_1, \mathcal{C}_2) \\ &+ \mathbb{P}(\mathcal{C}_1, \mathcal{AT}_2)\Delta_2^0(\mathcal{C}_1, \mathcal{AT}_2) + \mathbb{P}(\mathsf{NT}_1, \mathcal{F}_2)\Delta_2^0(\mathsf{NT}_1, \mathcal{F}_2). \end{aligned}$$

• We want to identify the target parameter $\Delta_2^1(C_1)$.

• Under Assumptions 1 and 2 only,

$$FS_{1}\Delta_{2}^{1}(C_{1}) = RF_{2} - \mathbb{P}(NT_{1}, C_{2})\Delta_{2}^{0}(NT_{1}, C_{2}) \\ + \mathbb{P}(C_{1}, AT_{2})\Delta_{2}^{0}(C_{1}, AT_{2}) + \mathbb{P}(NT_{1}, F_{2})\Delta_{2}^{0}(NT_{1}, F_{2}).$$

- We want to identify the target parameter $\Delta_2^1(C_1)$.
- ► We observe directly the first stage and the reduced form.

• Under Assumptions 1 and 2 only,

 $FS_{1}\Delta_{2}^{1}(C_{1}) = RF_{2} - \mathbb{P}(NT_{1}, C_{2})\Delta_{2}^{0}(NT_{1}, C_{2}) \\ + \mathbb{P}(C_{1}, AT_{2})\Delta_{2}^{0}(C_{1}, AT_{2}) + \mathbb{P}(NT_{1}, F_{2})\Delta_{2}^{0}(NT_{1}, F_{2}).$

- We want to identify the target parameter $\Delta_2^1(C_1)$.
- We observe directly the first stage and the reduced form.
- <u>Assume</u> bounds on the treatment effects, $\overline{\Delta}$ and $\underline{\Delta}$ (natural if Y is bounded).

• Under Assumptions 1 and 2 only,

 $FS_{1}\Delta_{2}^{1}(C_{1}) = RF_{2} - \mathbb{P}(NT_{1}, C_{2})\Delta_{2}^{0}(NT_{1}, C_{2})$ $+ \mathbb{P}(C_{1}, AT_{2})\Delta_{2}^{0}(C_{1}, AT_{2}) + \mathbb{P}(NT_{1}, F_{2})\Delta_{2}^{0}(NT_{1}, F_{2}).$

- We want to identify the target parameter $\Delta_2^1(C_1)$.
- ▶ We observe directly the first stage and the reduced form.
- <u>Assume</u> bounds on the treatment effects, $\overline{\Delta}$ and $\underline{\Delta}$ (natural if Y is bounded).
- Bounds on the probabilities:
 - ★ $\mathbb{P}(NT_1, C_2)$: at most, prob of switching into treatment at t = 2 given $Z_i = 1$;
 - ★ $\mathbb{P}(C_1, AT_2) + \mathbb{P}(NT_1, F_2)$: at most, prob of switching into treatment at t = 2 for $Z_i = 0$.

• Given that,

$$\frac{RF_2}{FS_1} - \frac{\mathbb{P}\left(D_{i,2} > D_{i,1} | Z_i = 1\right)}{FS_1}\overline{\Delta} + \frac{\mathbb{P}\left(D_{i,2} > D_{i,1} | Z_i = 0\right)}{FS_1}\underline{\Delta}$$

is a lower bound for $\Delta_2^1(C_1)$, and

$$\frac{\mathsf{RF}_2}{\mathsf{FS}_1} - \frac{\mathbb{P}\left(\mathsf{D}_{i,2} > \mathsf{D}_{i,1} | Z_i = 1\right)}{\mathsf{FS}_1} \underline{\Delta} + \frac{\mathbb{P}\left(\mathsf{D}_{i,2} > \mathsf{D}_{i,1} | Z_i = 0\right)}{\mathsf{FS}_1} \overline{\Delta}$$

is an upper bound.

Partial Identification: Tighter Bounds

Assumption 5

For all $g, g' \in \{(C_1, AT_2), (NT_1, C_2), (NT_1, F_2)\}$ with $\mathbb{P}(g) > 0$ and $\mathbb{P}(g') > 0$, $\Delta_2^0(g) = \Delta_2^0(g')$.

• If Assumption 5 holds,

$$\frac{\mathsf{RF}_2}{\mathsf{FS}_1} + \left[1(\mathsf{FS}_2 \leq \mathsf{FS}_1)\underline{\Delta} + 1(\mathsf{FS}_2 > \mathsf{FS}_1)\overline{\Delta}\right]\frac{\mathsf{FS}_1 - \mathsf{FS}_2}{\mathsf{FS}_1},$$

is a lower bound for $\Delta_2^1(C_1)$ and

$$\frac{\textit{RF}_2}{\textit{FS}_1} + \left[1(\textit{FS}_2 \leq \textit{FS}_1)\overline{\Delta} + 1(\textit{FS}_2 > \textit{FS}_1)\underline{\Delta}\right]\frac{\textit{FS}_1 - \textit{FS}_2}{\textit{FS}_1}$$

is an upper bound.

- These bounds are (weakly) tighter than the previous ones.
 - Intuition: under these assumptions, we don't need bounds on the probabilities.

Conclusion

• Setting:

Static instrument and dynamic compliance.

Results:

- Decomposition: possibility of negative weights.
- ► Identification: require a different type of treatment effect homogeneity assumption.
- Partial identification: relax these assumptions.

Related Literature

- IV:
 - Static IV: Lundborg et al. (2017) and Miquel (2002).
 - ▶ IV in a general dynamic setting: Han (2021).
 - Lower Dimensional IV: Angrist and Imbens (1995), Torgovitsky (2015), D'Haultfœuille and Février (2015), Masten and Torgovitsky (2016), Caetano and Escanciano (2021) and Hull (2018).
 - ▶ IV with covariates: Kolesár (2013), Blandhol et al. (2022) and Słoczyński (2022).
- Dynamic Causal Effects: Ding and Lehrer (2010), Heckman et al. (2016), Bojinov et al. (2021), van den Berg and Vikström (2022).
- DiD:
 - ▶ Fuzzy DiD: Hudson et al. (2017), de Chaisemartin and D'Haultfœuille (2017) and Picchetti and Pinto (2022).
 - Variation in Timing of Treatment: de Chaisemartin and D'Haultfœuille (2020), Callaway and Sant'Anna (2021), Sun and Abraham (2021), Goodman-Bacon (2021), Athey and Imbens (2022) and Borusyak et al. (2023).
- Recursive identification in RDD: Cellini et al. (2010).

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