

How Likely is it that Omitted Variable Bias will Overturn your Results?

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August 26–30, 2024
ESEM 2024

Question and Outline

Main question

- Question: Can we quantify the possibility of omitted variable bias overturning reported results in a linear model?
 - Result is understood to be overturned if zero is contained in the confidence interval for the true parameter
- I provide an affirmative answer by building on Cinelli and Hazlett (2020)
- This paper connects to the literature on sensitivity analysis: Frank, 2000; Krauth, 2016; Ding and VanderWeele, 2016; VanderWeele and Ding, 2017; Oster, 2019; Cinelli and Hazlett (2020); Diegert et al., 2023,

Question and Outline

Outline of talk

- Omitted variable bias using partial R^2
- Benchmark covariate (or group of covariates) + 2 sensitivity parameters, k_D, k_Y
- Cinelli and Hazlett (2020) show how to compute bias-adjusted estimate and confidence interval for specific values of k_D, k_Y
- Easier to justify a range, rather than specific values of k_D, k_Y
- Once range of k_D, k_Y is chosen, we can compute a probability of OVB overturning result
- Discuss an example

Set Up

- Full model:

$$Y = \hat{\tau}D + X\hat{\beta} + \hat{\gamma}Z + \hat{\varepsilon}_{\text{full}}$$

- Restricted model:

$$Y = \hat{\tau}_{\text{res}}D + X\hat{\beta}_{\text{res}} + \hat{\varepsilon}_{\text{res}}$$

- Omitted variable bias:

$$\widehat{\text{bias}} = \hat{\tau}_{\text{res}} - \hat{\tau}$$

- Y : outcome variable
- D : treatment variable (scalar)
- X : vector of control variables
- Z : unobserved confounder (omitted variable)

Set Up

Using the FWL theorem and definitions of partial R^2 , Cinelli and Hazlett (2020) show that

- Expression for the absolute value of the omitted variable bias:

$$|\widehat{\text{bias}}| = \widehat{\text{se}}(\hat{\tau}_{\text{res}}) \sqrt{\frac{df \times R_{Y \sim Z|D,X}^2 \times R_{D \sim Z|X}^2}{1 - R_{D \sim Z|X}^2}}$$

- Expression for standard error of the true estimate, $\hat{\tau}$:

$$\widehat{\text{se}}(\hat{\tau}) = \widehat{\text{se}}(\hat{\tau}_{\text{res}}) \sqrt{\frac{1 - R_{Y \sim Z|D,X}^2}{1 - R_{D \sim Z|X}^2} \times \frac{df}{df - 1}}$$

- $R_{Y \sim Z|D,X}^2$: partial R^2 of Y and Z , conditional on D, X
- $R_{D \sim Z|X}^2$: partial R^2 of D and Z , conditional on X
- se : standard error
- df : degrees of freedom of restricted regression

What is partial R^2 ?

The definition of the partial R^2 is

$$R_{Y \sim Z|X}^2 = \frac{R_{Y \sim Z+X}^2 - R_{Y \sim X}^2}{1 - R_{Y \sim X}^2}$$

- Numerator: increment in total R^2 when Z is added to a regression of Y on X
- Denominator: 1 minus total R^2 in a regression of Y on X

Main Proposal

- If we knew $R_{Y \sim Z|D, X}^2$ and $R_{D \sim Z|X}^2$, we could
 - compute $|\widehat{\text{bias}}|$ and $\widehat{\text{se}}(\hat{\tau})$
 - and use it to construct bias-adjusted treatment effect and bias-adjusted confidence intervals
- Case 1: When estimated treatment effect, $\hat{\tau}_{\text{res}}$, is positive
 - bias-adjusted estimate: $\hat{\tau} = \hat{\tau}_{\text{res}} - |\widehat{\text{bias}}|$
 - bias-adjusted confidence interval (significance level α) for τ (true value):

$$(\hat{\tau}_{\text{res}} - |\widehat{\text{bias}}| - |t_{\alpha/2}^*| \widehat{\text{se}}(\hat{\tau}), \hat{\tau}_{\text{res}} - |\widehat{\text{bias}}| + |t_{\alpha/2}^*| \widehat{\text{se}}(\hat{\tau}))$$

where $|t_{\alpha/2}^*|$ is the absolute magnitude of the critical value.

- Case 2: When estimated treatment effect, $\hat{\tau}_{\text{res}}$, is negative
 - bias-adjusted estimate: $\hat{\tau} = \hat{\tau}_{\text{res}} + |\widehat{\text{bias}}|$
 - bias-adjusted confidence interval (significance level α) for τ :

$$(\hat{\tau}_{\text{res}} + |\widehat{\text{bias}}| - |t_{\alpha/2}^*| \widehat{\text{se}}(\hat{\tau}), \hat{\tau}_{\text{res}} + |\widehat{\text{bias}}| + |t_{\alpha/2}^*| \widehat{\text{se}}(\hat{\tau}))$$

Main Proposal

- We do not know $R_{Y \sim Z|D,X}^2$ and $R_{D \sim Z|X}^2$ because Z is unobserved
- What do we do?
 - We choose a (group of) *benchmark* covariate(s) from X (set of included regressors): X_j
 - We define two sensitivity parameters, k_D, k_Y
 - k_D : captures relative strength of association of $Z^{\perp X}$ (part of omitted variable orthogonal to covariates) with D (treatment variable) compared to benchmark covariate(s) with D
 - k_Y : captures relative strength of association of $Z^{\perp X}$ (part of omitted variable orthogonal to covariates) with Y (outcome variable) compared to benchmark covariate(s) with Y
 - Strength of association can be measured in three ways
 - Total R^2
 - Partial R^2 without conditioning on D
 - Partial R^2 with conditioning on D

Main Proposal

- Total R^2 -based benchmarking:

$$k_D := \frac{R_{D \sim Z^{\perp X}}^2}{R_{D \sim X_j}^2}, \quad k_Y := \frac{R_{Y \sim Z^{\perp X}}^2}{R_{Y \sim X_j}^2}$$

- Partial R^2 -based benchmarking without conditioning on treatment variable:

$$k_D := \frac{R_{D \sim Z^{\perp X} | X_{-j}}^2}{R_{D \sim X_j | X_{-j}}^2}, \quad k_Y := \frac{R_{Y \sim Z^{\perp X} | X_{-j}}^2}{R_{Y \sim X_j | X_{-j}}^2}$$

- Partial R^2 -based benchmarking with conditioning on treatment variable (for k_Y):

$$k_D := \frac{R_{D \sim Z^{\perp X} | X_{-j}}^2}{R_{D \sim X_j | X_{-j}}^2}, \quad k_Y := \frac{R_{Y \sim Z^{\perp X} | X_{-j}, D}^2}{R_{Y \sim X_j | X_{-j}, D}^2}$$

Main Proposal

For any value of k_D , k_Y , we can compute what we need

- For total R^2 -based benchmarking, we have

$$R_{D \sim Z|X}^2 = \frac{k_D R_{D \sim X_j}^2}{1 - R_{D \sim X}^2}, \quad R_{Y \sim Z|X}^2 = \frac{k_Y R_{Y \sim X_j}^2}{1 - R_{Y \sim X}^2}.$$

- For partial R^2 -based benchmarking without conditioning on treatment variable, we have

$$R_{D \sim Z|X}^2 = \frac{k_D R_{D \sim X_j|X_{-j}}^2}{1 - R_{D \sim X_j|X_{-j}}^2}, \quad R_{Y \sim Z|X}^2 = \frac{k_Y R_{Y \sim X_j|X_{-j}}^2}{1 - R_{Y \sim X_j|X_{-j}}^2}$$

- In both cases, we then compute

$$R_{Y \sim Z|D,X}^2 = \frac{(|R_{Y \sim Z|X}| - |R_{Y \sim D|X}| |R_{D \sim Z|X}|)^2}{(1 - R_{Y \sim D|X}^2)(1 - R_{D \sim Z|X}^2)}.$$

Main Proposal

- For partial R^2 -based benchmarking with conditioning on treatment variable:

$$R_{D \sim Z|X}^2 = \frac{k_D R_{D \sim X_j|X_{-j}}^2}{1 - R_{D \sim X_j|X_{-j}}^2}, \quad R_{Y \sim Z|D,X}^2 = \eta^2 f_{Y \sim X_j|X_{-j},D}^2$$

where

$$\eta = \frac{\sqrt{k_Y} + |f_{k_D} \times f_{D \sim X_j|X_{-j}}|}{\sqrt{1 - f_{k_D}^2 \times f_{D \sim X_j|X_{-j}}^2}}$$

and

$$f_{D \sim X_j|X_{-j}}^2 = \frac{R_{D \sim X_j|X_{-j}}^2}{1 - R_{D \sim X_j|X_{-j}}^2} \quad f_{k_D} = \frac{\sqrt{k_D R_{D \sim X_j|X_{-j}}^2}}{\sqrt{1 - k_D R_{D \sim X_j|X_{-j}}^2}}$$

Main Proposal

- Since $0 \leq R_{D \sim Z|X}^2 \leq 1$ and $0 \leq R_{Y \sim Z|D,X}^2 \leq 1$, this gives us permissible values of k_D and k_Y .
- Example: For total R^2 -based benchmarking, we have

$$R_{D \sim Z|X}^2 = \frac{k_D R_{D \sim X_j}^2}{1 - R_{D \sim X}^2}, \quad R_{Y \sim Z|X}^2 = \frac{k_Y R_{Y \sim X_j}^2}{1 - R_{Y \sim X}^2}$$

and so, we have

$$0 \leq k_D \leq \frac{1 - R_{D \sim X}^2}{R_{D \sim X_j}^2} = k_D^{\max}$$

and

$$0 \leq k_Y \leq \frac{1 - R_{Y \sim X}^2}{R_{Y \sim X_j}^2} = k_Y^{\max}$$

Main Proposal: Summary

- For any value of k_D, k_Y , we compute $R_{Y \sim Z|D,X}^2$ and $R_{D \sim Z|X}^2$
- And we get bias-adjusted estimate and confidence intervals for our choice of k_D, k_Y
- Then we compute
 - contour plots of lower (or upper) boundary of confidence interval over *all permissible* values of $k_D, k_Y \Rightarrow$ look at level 0
 - if estimated effect is positive, look at lower boundary
 - if estimated effect is negative, look at upper boundary
 - probability that OVB can overturn reported result
 - When estimated treatment effect is positive, this is

$$1 - \left(\frac{\text{area where lower boundary of conf int is } > 0}{\text{valid area of contour area}} \right)$$

- When estimated treatment effect is negative, this is

$$1 - \left(\frac{\text{area where lower boundary of conf int is } < 0}{\text{valid area of contour area}} \right)$$

Example

$$\text{PeaceIndex}_i = \beta_0 + \beta_1 \text{DirectHarm}_i + \text{Controls}_i + \varepsilon_i,$$

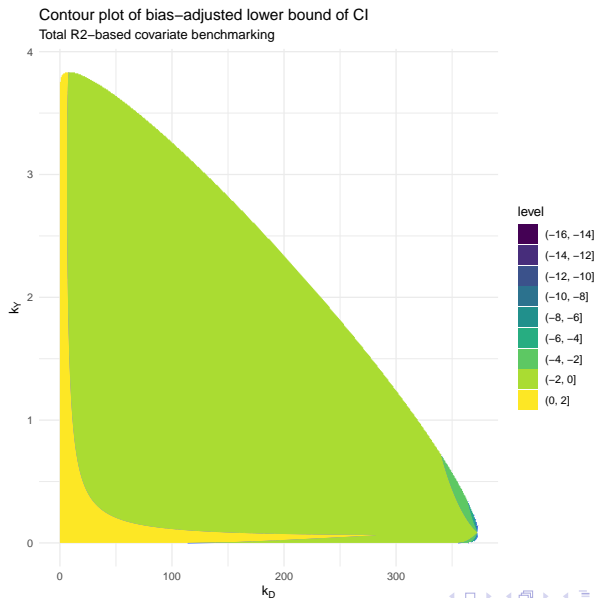
- i index for individual
- PeaceIndex (outcome, Y): index of attitude towards peace efforts
- DirectHarm (treatment, D): measures the exposure to violence
- Control variables, X : gender of the individual, age, whether the individual was a farmer, herder, merchant or trader, household size, whether or not the individual voted in the past, and village-level fixed effects.
- Omitted variable, Z : wealth
- Benchmark, X_j : gender of the individual

Bias-adjusted estimate and confidence interval

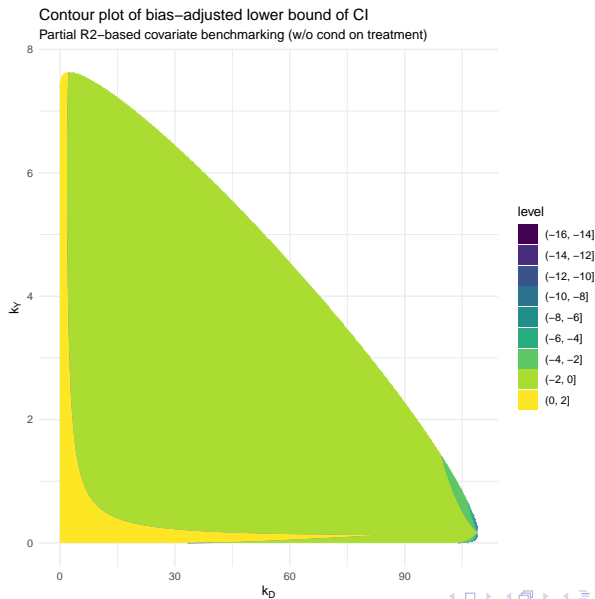
| | Panel A: $k_D = 1, k_Y = 1$ | | | Panel B: $k_D = 3, k_Y = 3$ | | |
|----------------------------------|-----------------------------|-----------|-----------|-----------------------------|-----------|-----------|
| | Total | Partial 1 | Partial 2 | Total | Partial 1 | Partial 2 |
| $R^2_{Y \sim D X}$ | 0.022 | 0.022 | 0.022 | 0.022 | 0.022 | 0.022 |
| $R^2_{D \sim Z X}$ | 0.003 | 0.009 | 0.009 | 0.008 | 0.027 | 0.027 |
| $R^2_{Y \sim Z D,X}$ | 0.259 | 0.125 | 0.125 | 0.781 | 0.381 | 0.374 |
| Estimate | 0.097 | 0.097 | 0.097 | 0.097 | 0.097 | 0.097 |
| Bias-Adj Estimate | 0.080 | 0.075 | 0.075 | 0.046 | 0.030 | 0.030 |
| Bias-Adj Standard Error | 0.020 | 0.022 | 0.022 | 0.011 | 0.019 | 0.019 |
| Lwr Bdary of Bias-Adj Conf. Int. | 0.041 | 0.032 | 0.032 | 0.024 | -0.007 | -0.006 |
| Upr Bdary of Bias-Adj Conf. Int. | 0.120 | 0.118 | 0.118 | 0.067 | 0.066 | 0.067 |

- Total: total R^2 -based covariate benchmarking
- Partial 1: partial R^2 -based covariate benchmarking without conditioning on treatment
- Partial 2: partial R^2 -based covariate benchmarking with conditioning on treatment

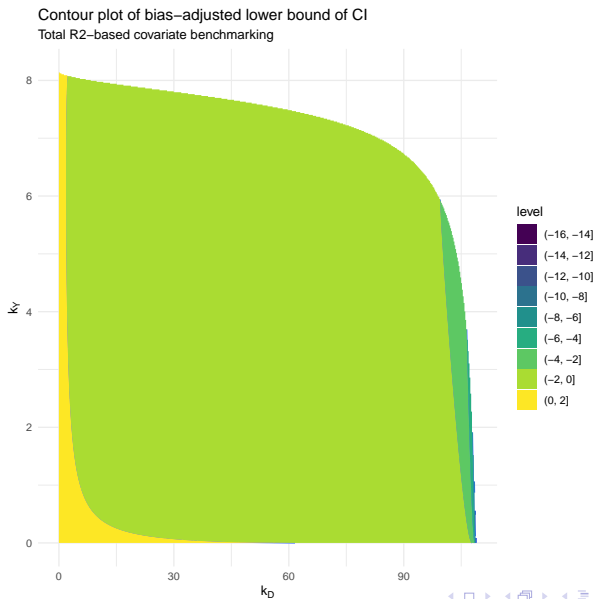
Contour plot (Total R^2)



Contour plot (Partial R^2 without conditioning)



Contour plot (Partial R^2 with conditioning)



Probability of reported result being overturned

| | Total | Partial 1 | Partial 2 |
|--|---------|-----------|-----------|
| Panel A: Full range: | | | |
| $0 \leq k_D \leq k_D^{\max}; 0 \leq k_Y \leq k_Y^{\max}$ | 0.925 | 0.925 | 0.960 |
| Panel B: Absolute upper bounds: | | | |
| $0 \leq k_D \leq 1; 0 \leq k_Y \leq 1$ | 0.000 | 0.000 | 0.000 |
| $0 \leq k_D \leq 3; 0 \leq k_Y \leq 3$ | 0.000 | 0.021 | 0.019 |
| $0 \leq k_D \leq 5; 0 \leq k_Y \leq 5$ | 0.000 | 0.336 | 0.335 |
| Panel C: Relative upper bounds: | | | |
| $0 \leq k_D \leq 0.1k_D^{\max}; 0 \leq k_Y \leq 0.1k_Y^{\max}$ | 0.046 | 0.046 | 0.116 |
| $0 \leq k_D \leq 0.25k_D^{\max}; 0 \leq k_Y \leq 0.25k_Y^{\max}$ | 0.628 | 0.628 | 0.701 |
| Memo: | | | |
| k_D^{\max} | 373.134 | 109.119 | 109.119 |
| k_Y^{\max} | 3.839 | 7.643 | 8.155 |

Probability of reported result being overturned

- Important message: result depends on choice of k_D^{\max} and k_Y^{\max}
- Full permissible range of k_D, k_Y gives very conservative answer
- Can we do better?
- Can we choose upper bounds for k_D, k_Y that are lower than k_D^{\max} and k_Y^{\max} ?
- Two possibilities
 - Absolute bounds
 - Relative bounds: better because it is based on the sample (which determines k_D^{\max} and k_Y^{\max})
- Some simulation evidence for a possible answer using relative bounds

Simulation Set-up

- X^s : standardized k -dimensional multivariate Gaussian of size N with mean $0_{k \times 1}$ and covariance matrix $A'A$ (with A coming from k^2 draws from $\text{uniform}(0,1)$)
- I generate the scalar treatment variable, D , as

$$D = a_0 + X_1^s a_1 + X_2^s a_2 + \cdots + X_{k-1}^s a_{k-1} + X_k^s a_k + u_D,$$

where $a = (a_0, a_1, \dots, a_k)$ is a $(k+1)$ -vector formed by drawing $k+1$ random numbers from a uniform distribution over $(-1, 1)$ and $u_D \sim \text{i.i.d.} N(0, \sigma_{u_D}^2)$.

- I generate the scalar outcome variable, Y , as

$$Y = b_0 + X_1^s b_1 + X_2^s b_2 + \cdots + X_{k-1}^s b_{k-1} + X_k^s b_k + u_Y,$$

where $b = (b_0, b_1, \dots, b_k)$ is a $(k+1)$ -vector formed by drawing $k+1$ random numbers from a uniform distribution over $(-1, 1)$ and $u_Y \sim \text{i.i.d.} N(0, \sigma_{u_Y}^2)$.

Simulation Set-up

- Y, D, X^s comprise the simulated data set.
- Using this data set, I estimate the following model using OLS,

$$Y = \beta_0 + D\tau + X_1^s\beta_1 + X_2^s\beta_2 + \cdots + X_{k-1}^s\beta_{k-1} + \varepsilon,$$

- I treat the k -th column of X^s as the unobserved confounder (the omitted variable) and *leave it out of the estimated model*, i.e. $Z = X_k^s$.
- I compute k_D and k_Y and k_D^{\max} and k_Y^{\max}
- I repeat this 1000 times
- Look at the empirical distribution of k_D/k_D^{\max} and k_Y/k_Y^{\max}

Simulation results

Table: 90-th percentile of the empirical distribution of k_d/k_d^{max} and k_y/k_y^{max}

| N | k = 10 | | k = 25 | | k = 50 | | k = 100 | |
|-------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|
| | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ |
| 250 | 0.408 | 0.398 | 0.206 | 0.213 | 0.126 | 0.106 | 0.074 | 0.067 |
| 500 | 0.433 | 0.435 | 0.212 | 0.210 | 0.115 | 0.109 | 0.061 | 0.057 |
| 1000 | 0.424 | 0.413 | 0.222 | 0.214 | 0.125 | 0.119 | 0.062 | 0.059 |
| 2500 | 0.385 | 0.413 | 0.190 | 0.179 | 0.107 | 0.113 | 0.057 | 0.053 |
| 5000 | 0.421 | 0.419 | 0.204 | 0.200 | 0.094 | 0.094 | 0.064 | 0.056 |
| 10000 | 0.422 | 0.417 | 0.202 | 0.190 | 0.119 | 0.115 | 0.056 | 0.064 |

- I have used $\sigma_{u_Y} = \sigma_{u_D} = 1$
- Main takeaways:
 - result depends on k but not on N
 - k_d/k_d^{max} and k_y/k_y^{max} fall as k increases

Simulation results

Table: 90-th percentile of the empirical distribution of k_d/k_d^{max} and k_y/k_y^{max}

| | $k = 10$ | | $k = 25$ | | $k = 50$ | | $k = 100$ | |
|--------------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|
| | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ | $\frac{k_d}{k_d^{max}}$ | $\frac{k_y}{k_y^{max}}$ |
| $\sigma_{u_Y} = \sigma_{u_D}$ | 0.42 | 0.44 | 0.20 | 0.21 | 0.11 | 0.11 | 0.06 | 0.06 |
| $\sigma_{u_Y} = 3\sigma_{u_D}$ | 0.43 | 0.08 | 0.21 | 0.03 | 0.10 | 0.02 | 0.06 | 0.01 |
| $3\sigma_{u_Y} = \sigma_{u_D}$ | 0.07 | 0.42 | 0.03 | 0.19 | 0.02 | 0.12 | 0.01 | 0.06 |
| $\sigma_{u_Y} = 5\sigma_{u_D}$ | 0.42 | 0.03 | 0.20 | 0.01 | 0.11 | 0.01 | 0.06 | 0.01 |
| $5\sigma_{u_Y} = \sigma_{u_D}$ | 0.03 | 0.41 | 0.01 | 0.20 | 0.01 | 0.11 | 0.01 | 0.05 |

- Benchmark case with $\sigma_{u_Y} = \sigma_{u_D}$ is most conservative
- When $\sigma_{u_Y} > \sigma_{u_D}$: same k_D/k_D^{max} but lower k_Y/k_Y^{max} than in benchmark case
- When $\sigma_{u_Y} < \sigma_{u_D}$, same k_Y/k_Y^{max} but lower k_D/k_D^{max} than in benchmark case

Probability of reported result being overturned

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