

<sup>1</sup>University of Orléans <sup>2</sup>HEC Paris  $34MSE$ 

Econometric Society European Meeting (ESEM)

August 26, 2024

S. Hué , C. Hurlin , C. Pérignon , S. Saurin Valley and Valley and University of Orléans HEC Paris AMSE

[Measuring the Driving Forces of Predictive Performance: Application to Credit Scoring](#page-28-0) 1/22 1/22

<span id="page-1-0"></span>

#### Figure:  $AUC = 0.78$



#### **What is the contribution of each feature to the AUC?**

<span id="page-2-0"></span>

We introduce the XPER (eXplainable PERformance) methodology to measure the specific contribution of the input features to the predictive performance of a model.

This method is based on:

- A Shapley Value decomposition (Shapley, 1953).
- A Performance Metric (PM).
- **•** Predictions  $\hat{y}$  of a regression or classification model  $f(.)$ .

<span id="page-3-0"></span>**[Introduction](#page-1-0)** [Framework](#page-4-0) [Theoretical Decomposition](#page-12-0) [Empirical Application](#page-22-0) [Conclusion](#page-28-0)<br>
000000 00000000 0000000 0000000 000000

## An intuitive primer on XPER



with  $\phi_0$  a benchmark value, and  $\phi_i$  the XPER contribution of feature  $x_i$  to the AUC of the model.

# <span id="page-4-0"></span>**Framework and Performance Metrics**

<span id="page-5-0"></span>

We consider a **classification** or a **regression** problem for which:

- $\bullet$  A dependent (target) variable denoted y takes values in  $\mathcal{Y}$ . In case of classification  $\mathcal{Y} = \{0, 1\}$ , and in case of regression  $\mathcal{Y} \subset \mathbb{R}$ .
- A q-vector  $\mathbf{x} \in \mathcal{X}$  refers to input (explanatory) features, with  $\mathcal{X} \subset \mathbb{R}^q$ .
- $\bullet$  We denote by  $f: \mathbf{x} \to \hat{y}$  a model, where  $\hat{y} \in \mathcal{Y}$  is either a classification or regression output, such as  $\hat{y} = f(\mathbf{x})$ .

<span id="page-6-0"></span>

- The econometric or machine learning model may be parametric or not, linear or not, individual or an ensemble classifier, etc.
- The model is estimated (parametric model) or trained (machine learning algorithm) once for all on an estimation or training sample  $\{ \mathbf{x}_j, y_j \}_{j=1}^T.$
- The statistical performance of the model is evaluated on a test sample  $S_n = {\mathbf{x}_i, y_i, \hat{f}(\mathbf{x}_i)}_{i=1}^n$  for *n* individuals.

#### <span id="page-7-0"></span>Definition

A sample performance metric  $PM_n \in \Theta \subseteq \mathbb{R}$  associated to the model  $\hat{f}(.)$  and a test sample  $S_n$  is a scalar defined as:

$$
PM_n = \tilde{G}_n(y_1, ..., y_n; \hat{f}(\mathbf{x_1}), ..., \hat{f}(\mathbf{x_n})) = G_n(\mathbf{y}; \mathbf{X}),
$$

where  ${\bf y} = (y_1, ..., y_n)^T$  and  ${\bf X} = (x_1, ..., x_n)^T$ .

#### **Examples:**

- **•** Regression model: MSE, MAE, R-squared.
- Classification model: AUC, Accuracy, Sensitivity, Specificity, Brier Score.  $\bullet$
- $\bullet$ Economic criteria: Profit or cost function.

<span id="page-8-0"></span>

### Assumption 1

The sample performance metric satisfies an additive property such that:

$$
G_n(\mathbf{y}; \mathbf{X}) = \frac{1}{n} \sum_{i=1}^n G(y_i; \mathbf{x}_i; \hat{\delta}_n),
$$

where  $G(y_i; \mathbf{x}_i; \delta_n)$  denotes an individual contribution to the performance metric and  $\hat{\delta}_n$  is a nuisance parameter which depends on the test sample  $S_n$ .

<span id="page-9-0"></span>

#### Assumption 1

The sample performance metric satisfies an additive property such that:

$$
G_n(\mathbf{y}; \mathbf{X}) = \frac{1}{n} \sum_{i=1}^n G(y_i; \mathbf{x}_i; \hat{\delta}_n),
$$

where  $G(y_i; \mathbf{x}_i; \delta_n)$  denotes an individual contribution to the performance metric and  $\hat{\delta}_n$  is a nuisance parameter which depends on the test sample  $S_n$ .

### Example (Mean Squared Error (MSE))

$$
G_n(\mathbf{y}; \mathbf{X}) = \frac{1}{n} \sum_{i=1}^n G(y_i; \mathbf{x}_i) = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{f}(\mathbf{x}_i))^2.
$$

### <span id="page-10-0"></span>Assumption 2

The sample performance metric  $G_n(\mathbf{y}; \mathbf{X}; \hat{\delta}_n)$  converges to the population performance metric  $\mathbb{E}_{\gamma, \mathbf{x}}(G(\gamma; \mathbf{x}; \delta_0))$ , where  $\mathbb{E}_{\gamma, \mathbf{x}}(.)$  refers to the expected value with respect to the joint distribution of y and **x**, and  $\delta_0 = \text{plim } \hat{\delta}_n$ .

<span id="page-10-1"></span>Example (Mean Squared Error (MSE))

$$
\mathbb{E}_{y,\mathbf{x}}(G(y;\mathbf{x};\delta_0))=\mathbb{E}_{y,\mathbf{x}}(y-\hat{f}(\mathbf{x}))^2.
$$

## <span id="page-11-0"></span>**Theoretical Decomposition**

<span id="page-12-0"></span>



<span id="page-13-0"></span>



<span id="page-14-0"></span>









<span id="page-17-0"></span>



<span id="page-18-0"></span>



### <span id="page-19-0"></span>Definition (XPER value)

The contribution of feature  $x_i$  to the performance metric is:

$$
\phi_j = \sum_{S \subseteq \mathcal{P}(\{x\} \setminus \{x_j\})} w_S \left[ \mathbb{E}_{\mathbf{x}^{\overline{S}}} \mathbb{E}_{y, x_j, \mathbf{x}^S} \left( G \left( y; \mathbf{x}; \delta_0 \right) \right) - \mathbb{E}_{x_j, \mathbf{x}^{\overline{S}}} \mathbb{E}_{y, \mathbf{x}^S} \left( G \left( y; \mathbf{x}; \delta_0 \right) \right) \right],
$$

with S a coalition, i.e., a subset of features, excluding the feature of interest  $x_i$ , |S| the number of features in the coalition, and  $\mathcal{P}(\{\mathbf{x}\}\setminus\{x_i\})$  the powerset of the set  $\{x\} \setminus \{x_i\}$ .

The XPER value  $\phi_i$  associated to feature  $x_i$  measures its weighted average marginal contribution to the performance metric over all feature coalitions.

### <span id="page-20-0"></span>Axiom 1. (Efficiency)

The sum of the XPER values  $\phi_i$ ,  $\forall j = 1, ..., q$  satisfies:



with *ϕ*<sup>0</sup> the performance metric associated to a population where the target variable is independent from all features considered in the model.

<span id="page-21-0"></span>

### Definition (Individual XPER)

The individual XPER value *ϕ*i*,*<sup>j</sup> associated to individual i is defined as:

$$
\phi_{i,j}(y_i; \mathbf{x}_i) = \sum_{S \subseteq \mathcal{P}(\{\mathbf{x}\} \setminus \{x_j\})} w_S \left[ \mathbb{E}_{\mathbf{x}^{\overline{S}}} \left( G \left( y_i; \mathbf{x}_i; \delta_0 \right) \right) - \mathbb{E}_{x_j, \mathbf{x}^{\overline{S}}} \left( G \left( y_i; \mathbf{x}_i; \delta_0 \right) \right) \right].
$$

For a given realisation  $(y_i, x_i)$ , the corresponding individual contribution to the performance metric can be broken down into:

$$
G(y_i; \mathbf{x}_i; \delta_0) = \phi_{i,0} + \sum_{j=1}^q \phi_{i,j},
$$

where  $\phi_{i,j}$  is the realisation of  $\phi_{i,j}(y_i; \mathbf{x}_i)$  and  $\phi_{i,0}$  is the realisation of  $\phi_{i,0}(y_i) = \mathbb{E}_{\mathbf{x}}(G(y_i; \mathbf{x}; \delta_0)).$ 

## <span id="page-22-0"></span>**Empirical Application**

<span id="page-23-0"></span>

**Database of auto loans provided by an international bank**:

- $\bullet$  Target variable  $y_i$ :
	- 1: Default
	- 0: No default
- 7,440 consumer loans
- 10 features:
	- 2 categorical features
	- 8 continuous features

<span id="page-24-0"></span>

### Table: XGBoost Performances



# <span id="page-25-0"></span>XPER decomposition

### Figure: XPER decomposition



## <span id="page-26-0"></span>Using XPER to boost model performance

### Figure: Two-step procedure using XPER



## <span id="page-27-0"></span>Using XPER to boost model performance

### Table: Model performances



# <span id="page-28-0"></span>Conclusion

- We introduce a methodology designed to **measure the feature contributions to the performance** of any regression or classification model.
- **Our methodology is theoretically grounded** on Shapley values and is both model-agnostic and performance metric-agnostic.
- In a loan default forecasting application, XPER appears to be able to significantly **boost out-of-sample performance**.

## Python package

### Figure: Github link

