

Framing and Ambiguity

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- ▷ **Framing matters for choice under ambiguity:** Maher and Kashima (1997), Esponda and Vespa (2016), Schneider, Leland and Wilcox (2018), Leland, Schneider, Wilcox (2019)

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- ▷ **Theoretical perspective:** bounded rational agent is not able to integrate all payoff-relevant details coherently

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- ▷ **Theoretical perspective:** bounded rational agent is not able to integrate all payoff-relevant details coherently
- ▷ **What if framing is unobservable?**

An Example of Ambiguity Framing

- ▷ Alice prepares for an exam
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- ▷ *What data is consistent with framing of ambiguity?*
- ▷ *Can the frames be identified from the behavior?*
- ▷ *How to connect the frames to become more consistent in choices?*

Model

Decision maker (DM) chooses from menus of Anscombe-Aumann acts

- ▷ X —arbitrary set of prizes
- ▷ ΔX — probability distributions with finite support on X
- ▷ S —finite set of states

- ▷ f, g, h, \dots —Anscombe-Aumann acts $S \rightarrow \Delta X$
- ▷ p, q, r, \dots —constant acts $p(s) = p \forall s \in S$

- ▷ A, B, \dots —non-empty compact sets of acts (menus) with finite set of potential prizes $\{x \in X \mid \exists f \in A \exists s \in S : f(s)(x) > 0\}$

Primitive: a subset of acts that could be chosen from a menu

- ▷ Choice correspondence $\emptyset \neq c(A) \subseteq A$
- ▷ Ways to observe choice correspondence:
 - Repeated observations of choices from each menu
 - Choices of a group of agents (population interpretation)

(A1) Framed Uncertainty:

- ▷ α : $c(A \cup B) \cap A \subseteq c(A)$
- ▷ **C- β** : for constant acts $c(A \cup B) \cap A \neq \emptyset \implies c(A) \subseteq c(A \cup B)$
- ▷ **Aizerman's Property**: $f \notin c(A \cup \{f\}) \implies c(A) \subseteq c(A \cup \{f\})$

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Recall that *WARP* is equivalent to [α and β]

- ▷ *WARP* holds for (menus of) constant acts
- ▷ Aizerman's Property relaxes β

- (A2) C-Independence:** $c(\lambda A + (1 - \lambda)p) = \lambda c(A) + (1 - \lambda)p$
- (A3) Strict Monotonicity:** $g(s) \notin c(\{f(s), g(s)\}) \forall s \implies g \notin c(\{f, g\})$
- (A4) Continuity:** $\{(A, f) \mid f \in c(A)\}$ is closed
- (A5) C-Non-Degeneracy:** $\exists p, q : \{p\} = c(\{p, q\})$

(A6) No C-Hedging: $f, p \in A \implies c(A) \subseteq c(A \cup \{\lambda f + (1 - \lambda)p\})$

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If *WARP* holds, follows from *C-Independence* and *Strict Monotonicity*

(A7) Indirect Ambiguity Aversion: for $h \in A$

$$h \notin c(A \cup \{f\}) \text{ and } h \notin c(A \cup \{g\}) \implies h \notin c(A \cup \{\lambda f + (1 - \lambda)g\})$$

Framed ambiguity representation (U, \mathcal{A})

- ▷ $U: \Delta X \rightarrow \mathbb{R}$ —vNM expected utility
- ▷ \mathcal{A} —non-empty closed family of non-empty compact convex sets of beliefs

$$c(B) = \bigcup_{P \in \mathcal{A}} \arg \max_{f \in B} W_P(f)$$

where

$$W_P(f) = \min_{\mu \in P} \sum_{s \in S} \mu(s) U(f(s))$$

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Theorem 1. *A choice correspondence $c(\cdot)$ has a framed ambiguity representation if and only if axioms 1–7 hold.*

Proposition. *Axioms 1–7 are independent.*

Definition: $P = \bigcap_{Q \in \mathcal{C}} Q \neq \emptyset$ is a *coherent intersection* of sets of beliefs in a closed (in Hausdorff metric) family \mathcal{C} if for any linear subspace \mathbb{T} of \mathbb{R}^S ,

$$\text{proj}_{\mathbb{T}} \left(\bigcap_{Q \in \mathcal{C}} P' \right) = \bigcap_{Q \in \mathcal{C}} \text{proj}_{\mathbb{T}}(Q).$$

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Theorem 2. Let $c(\cdot)$ satisfy axioms 1–7. Then there is a unique minimum family of frames \mathcal{A} , a unique maximum family of frames \mathcal{B} and VNM expected utility function U such that:

- (i) (U', \mathcal{A}') represents $c(\cdot)$ if and only if $U' \approx U$, and $\mathcal{A} \subseteq \mathcal{A}' \subseteq \mathcal{B}$;
- (ii) $P \in \mathcal{B}$ if and only if P is a coherent intersection of some $\mathcal{C} \subseteq \mathcal{A}$.

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Corollary. If all frames $P \in \mathcal{A}$ are singletons, then \mathcal{A} is unique.

Comparative Statics

Definition: DM 1 is *more consistent* than DM 2 if for all menus A
 $|c_2(A)| = 1 \implies |c_1(A)| = 1$.

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Alternative characterization:

Proposition. Let $c_1(\cdot)$ and $c_2(\cdot)$ satisfy axioms 1–7. Then DM 1 is more consistent than DM 2 if and only if $c_1(\{f, g\}) \subseteq c_2(\{f, g\})$ for all acts f, g .

Crès, Gilboa, and Vieille (2011): let λ be convex weights: $\lambda_i \geq 0$, $\sum_{i=1}^N \lambda_i = 1$;

$$P = \sum_{i=1}^N \lambda_i P_i \equiv \left\{ \mu \in \Delta S \mid \exists \mu_i \in P_i : \mu = \sum_{i=1}^N \lambda_i \mu_i \right\}$$

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Observation. $DM(U, \sum_{i=1}^N \lambda P_i)$ is more consistent than $DM(U, \{P_1, \dots, P_N\})$

Crès, Gilboa, and Vieille (2011):

$$P = \text{conv} \left(\bigcup_{Q \in \mathcal{C}} Q \right), \text{ where } \mathcal{C} \text{ is non-empty and closed}$$

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Observation. $\text{DM} \left(U, \text{conv} \left(\bigcup_{Q \in \mathcal{C}} Q \right) \right)$ is more consistent than $\text{DM} (U, \mathcal{A})$ if $\mathcal{C} \subseteq \mathcal{A}$

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Observation. DM $(U, \bigcap_{Q \in \mathcal{C}} Q)$ is more consistent than DM (U, \mathcal{A}) if $\mathcal{C} \subseteq \mathcal{A}$,
and the intersection $\bigcap_{Q \in \mathcal{C}} Q$ is coherent

Definition: Given a compact collection of frames \mathcal{A} , its closure with respect to operations of convex combination, convex union and coherent intersection is the minimum compact collection of frames $\Gamma(\mathcal{A})$ such that:

(i) $\forall \{P_1, \dots, P_N\} \subseteq \Gamma(\mathcal{A}) \forall \lambda \quad \sum_{i=1}^N \lambda_i P_i \in \Gamma(\mathcal{A});$

(ii) $\forall \mathcal{C} \subseteq \Gamma(\mathcal{A})$ if \mathcal{C} non-empty, closed, then $\text{conv}(\bigcup_{P \in \mathcal{C}} P) \in \Gamma(\mathcal{A});$

(iii) $\forall \mathcal{C} \subseteq \Gamma(\mathcal{A})$ if $\bigcap_{P \in \mathcal{C}} P$ is coherent, then $\bigcap_{P \in \mathcal{C}} P \in \Gamma(\mathcal{A}).$

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(iii) $\forall \mathcal{C} \subseteq \Gamma(\mathcal{A})$ if $\bigcap_{P \in \mathcal{C}} P$ is coherent, then $\bigcap_{P \in \mathcal{C}} P \in \Gamma(\mathcal{A}).$

Remark: $\Gamma(\mathcal{A})$ is well-defined.

Theorem 3. *Consider decision makers 1 and 2 represented by models (U_1, \mathcal{A}_1) and (U_2, \mathcal{A}_2) , where \mathcal{A}_2 is finite. Then the following statements are equivalent:*

- (i) *DM 1 is more consistent than DM 2;*
- (ii) *$U_1 \approx U_2$, and $\mathcal{A}_1 \subseteq \Gamma(\mathcal{A}_2)$;*
- (iii) *$U_1 \approx U_2$, and any $P \in \mathcal{A}_1$ is a coherent intersection of convex unions of convex combinations of frames in \mathcal{A}_2 .*

An Application to Aggregation of Preferences

- ▷ A group of (maxmin) ambiguity averse agents agree on utilities but disagree on beliefs
- ▷ Want to aggregate their preferences into a (maxmin) representative

Definition. A preference relation \succeq satisfies *Unanimity* with respect to $\{\succeq_i\}_{i=1}^N$ if $[f \succeq_i g \ \forall i = 1, \dots, N]$ implies $f \succeq g$.

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Corollary. Let $\{\succeq_i\}_{i=1}^N$ and \succeq admit maxmin representations with the same utility index and different sets of beliefs $\{P_i\}_{i=1}^N$ and P . Then \succeq satisfies *Unanimity* with respect to $\{\succeq_i\}_{i=1}^N$ if and only if P is a coherent closure of convex unions of convex combinations of $\{P_1, \dots, P_N\}$.

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Corollary. Framed ambiguity models (U, \mathcal{A}) and (U', \mathcal{A}') with $|\mathcal{A}|, |\mathcal{A}'| < \infty$ represent \succeq if and only if $U \approx U'$ and $\Gamma(\mathcal{A}) = \Gamma(\mathcal{A}')$.

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Remark. There is \succeq such that its framed ambiguity representations do not admit a minimum family of frames.

Proposition. Let (U, \mathcal{A}) represents $c_2(\cdot)$, and either Condition 1 or Condition 2 holds for \mathcal{A} . Then the following statements are equivalent:

(i) $c_1(\cdot)$ satisfies WARP and Continuity, and

$$f \in c_1(\{f, p\}) \iff \exists \text{ decomposition } \begin{cases} \lambda f + (1 - \lambda)q = \sum_{i=1}^k \sigma_i f_i \\ \forall i f_i \in c_2(\{f_i, \lambda p + (1 - \lambda)q\}) \end{cases}$$

(ii) $c_1(\cdot)$ is represented by the maxmin model $(U, \bigcap_{Q \in \mathcal{A}} Q)$.

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Condition 1: \mathcal{A} is finite, $\bigcap_{Q \in \mathcal{A}} Q \neq \emptyset$, and each $P \in \mathcal{A}$ is polyhedral.

Condition 2: \mathcal{A} is finite, and $\bigcap_{P \in \mathcal{A}} ri(P)$ is non-empty.

Literature and Conclusion

- ▷ Gilboa and Schmeidler (1989), Salant and Rubinstein (2008)
- ▷ Lu (2014), Kopylov (2021), Chandrasekher, Frick, Iijima, and Yaouang (2022), Stoye (2011)
- ▷ Lehrer and Teper (2011), Heller (2012)
- ▷ Bourgeois-Gironde and Giraud (2009), Ahn and Ergin (2010), Caplin and Martin (2020)
- ▷ Ok, Ortoleva, and Riella (2012), Galaabaatar and Karni (2013), Hara, Ok, and Riella (2019)
- ▷ Crès, Gilboa, and Vieille (2011), Hill (2011)

- ▷ A model of framing under Knightian Uncertainty is developed
- ▷ The analyst identifies the minimum set of frames from the choice
- ▷ The agent becomes less susceptible to framing by combining frames in cautious, optimistic way, or by linear combination

Supplementary Slides

Recall that utility representation \approx *WARP* = conditions $\alpha + \beta$:

▷ α : $c(A \cup B) \cap A \subseteq c(A)$

▷ β : $c(A \cup B) \cap A \neq \emptyset \implies c(A) \subseteq c(A \cup B)$

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Weaker than $\alpha + \beta = \text{WARP}$. For example, CAN HAVE:

- $c(\{f, g\}) = \{f, g\}$;
- $c(\{f, h\}) = \{f, h\}$;
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h is not chosen from $\{f, g, h\}$, although g and f are chosen, and h "is as good as g and f in pairwise comparisons."

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But, CANNOT HAVE:

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- $c(\{g, h\}) = \{g, h\}$;
- $c(\{f, g, h\}) = \{f\}$.

(A1) Framed Uncertainty:

- ▷ α : $c(A \cup B) \cap A \subseteq c(A)$
- ▷ $C\text{-}\beta$: for constant acts $c(A \cup B) \cap A \neq \emptyset \implies c(A) \subseteq c(A \cup B)$
- ▷ **Aizerman's Property**: $f \notin c(A \cup \{f\}) \implies c(A) \subseteq c(A \cup \{f\})$

But, CANNOT HAVE:

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Remark. $cl(\{P(B) | B \text{ is maximal for interior } f\})$ is the *minimum* family of frames that must be part of any representation of c .

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Relation to Other Axioms

Define $f \succeq g$ iff $\exists A : g \in A, f \in c(A)$. Under α , $f \succeq g$ iff $f \in c(\{f, g\})$

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Proposition 2

Let (U, \mathcal{A}) represents $c(\cdot)$. Then $|\mathcal{A}| = 1$ is equivalent to $c(\cdot)$ satisfying any of the following properties: β , WARP, Revealed Preference Rationality, γ , Normality, Ambiguity Aversion, Pairwise No-C-Hedging.

Definition: DM 1 is *more decisive* than DM 2 if $c_1 \subseteq c_2$.

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Proposition

Let $c_1(\cdot)$ and $c_2(\cdot)$ be represented by (U_1, \mathcal{A}_1) and (U_2, \mathcal{A}_2) . Then DM 1 is more decisive than DM 2 if and only if $U_1 \approx U_2$, and \mathcal{A}_1 is a subset of the maximum family of frames representing $c_2(\cdot)$.

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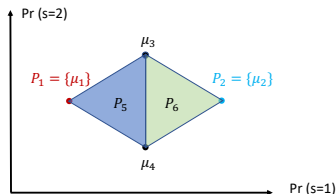
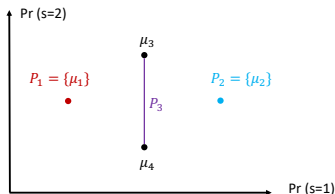
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Unanimity \iff *EUA* \iff convex combinations + convex unions

- ▷ Hill (2012) imposes “Weak Independence” axiom that connects aggregation rules for different preferences’ profiles

Unanimity + *WI* \iff convex combinations + convex unions

Non-Existence of a Minimum Family of Frames Representing \mathcal{A}



- ▷ $\mathcal{A} = \{P_1, P_2, P_3\}$ (left plot)
- ▷ $\mathcal{A}' = \{P_1, P_2, P_5, P_6\}$ (right plot)
- ▷ $P_5 = \text{conv}(P_1 \cup P_3)$, $P_6 = \text{conv}(P_2, P_3)$, hence $\mathcal{A}' \in \Gamma(\mathcal{A})$
- ▷ $P_3 = P_5 \cap P_6$, and the intersection is coherent, hence $\mathcal{A} \in \Gamma(\mathcal{A}')$

Proposition. *Let (U, \mathcal{A}) represents $c_2(\cdot)$, and $(V, \{P\})$ represents $c_1(\cdot)$. Then the following statements are equivalent:*

- (i) *If $f_i \in c_2(\{f_i, p\})$ for all $i = 1, \dots, k$, then $\sum_i^k \sigma_i f_i \in c_1\left(\left\{\sum_i^k \sigma_i f_i, p\right\}\right)$ for all convex weights σ .*
- (ii) *V is a positive affine transformation of U , and $P \subseteq \bigcap_{Q \in \mathcal{A}} Q \neq \emptyset$.*