Organized Information Transmission

Laurent Mathevet

& Ina Taneva

European University Institute

University of Edinburgh

European Meeting of the Econometric Society Barcelona School of Economics August 30th 2023

Question: What outcomes can be implemented by simple, realistic information protocols?

Question: What outcomes can be implemented by simple, realistic information protocols?

Observation: In reality, information is often transmitted in horizontal or vertical ways.

Horizontal transmission refers to informing a group of listeners simultaneously and symmetrically.

Horizontal transmission refers to informing a group of listeners simultaneously and symmetrically.

 Examples: academic seminars, board meetings, press conferences, etc. Horizontal transmission refers to informing a group of listeners simultaneously and symmetrically.

- Examples: academic seminars, board meetings, press conferences, etc.
- Transmitting information to many people at once, instead of to each of them individually, minimizes the number of communication channels.

Vertical transmission refers to information passed down sequentially and potentially asymmetrically from one individual to another. Vertical transmission refers to information passed down sequentially and potentially asymmetrically from one individual to another.

 Examples: hierarchical communication in organizations, viral marketing, etc. Vertical transmission refers to information passed down sequentially and potentially asymmetrically from one individual to another.

- Examples: hierarchical communication in organizations, viral marketing, etc.
- Delegating information transmission to the receivers themselves also minimizes the number of communication channels.

Contribution

Formalize the concepts of horizontal and vertical transmission.

Contribution

Formalize the concepts of horizontal and vertical transmission.

Focus on two limit-case families of information structures as proof of concept.

Formalize the concepts of horizontal and vertical transmission. Focus on two limit-case families of information structures as proof of concept.

Characterize the outcomes they implement in general finite games.

of concept.

Formalize the concepts of horizontal and vertical transmission. Focus on two limit-case families of information structures as proof

Characterize the outcomes they implement in general finite games. \Rightarrow Organizational perspective on incomplete information/ constrained information design. Formalize the concepts of horizontal and vertical transmission. Focus on two limit-case families of information structures as proof of concept.

Characterize the outcomes they implement in general finite games. \Rightarrow Organizational perspective on incomplete information/ constrained information design.

Optimality in binary-action environments with complementarities.

Formalize the concepts of horizontal and vertical transmission. Focus on two limit-case families of information structures as proof of concept.

Characterize the outcomes they implement in general finite games. \Rightarrow Organizational perspective on incomplete information/ constrained information design.

Optimality in binary-action environments with complementarities. ⇒ When optimal outcomes can be implemented by simple protocols. (E.g., optimality of posted prices in mechanism design.) In comparison, direct information structures, which invoke the Revelation Principle (Myerson (1991)) and make incentive-compatible action recommendations, do not constrain information horizontally or vertically.

This can make them very difficult to implement in reality.

"The Revelation Principle in mechanism design is both a blessing and a curse [...] It is a curse because direct mechanisms provide such an unrealistic picture of decision-making in organizations."

Van Zandt (2007)

Solution Concepts Forges (1993, 2006), Bergemann & Morris (2016) Information Design

Binary action supermodular: Arieli & Babichenko (2019), Candogan & Drakopoulos (2020), Candogan (2020)

Adversarial selection: Morris, Oyama & Takahashi (2020), Li, Song & Zhao (2019), Inostroza & Pavan (2020), Mathevet, Perego & Taneva (2020)

Structure of Information Brooks, Frankel & Kamenica (2022), Galperti & Perego (2020)

Communication in Organizations Radner (1993), Van Zandt (1999), Hori (2006), Crémer, Garicano & Prat (2007), Rantakari (2008), Alonso, Dessein & Matouschek (2008), Deimen & Szalay (2019)

Mechanism Design under Restricted Communication Mookherjee & Reichelstein (2001), Mookherjee & Tsumagari (2014)

Preliminaries

- Set of players: $\mathcal{I} = \{1, \ldots, n\}$.
- Uncertain state: $\omega \in \Omega$ (finite).
- Prior: $\mu \in \Delta(\Omega)$.
- Actions: $a_i \in A_i$ (finite).
- Payoffs: $u_i : A \times \Omega \rightarrow \mathbb{R}$.

• Outcome distribution: $p \in \Delta(A \times \Omega)$.



11

- Outcome distribution: $p \in \Delta(A \times \Omega)$.
- An outcome distribution p ∈ BCE(µ) if [Bergemann and Morris 2016]
 - **1.** Consistency with prior: $p(A \times \{\omega\}) = \mu(\omega)$ for all ω , and
 - **2.** Obedience: $\sum_{\omega} \sum_{a_{-i}} p(a, \omega) \left(u_i(a; \omega) u_i(a'_i, a_{-i}; \omega) \right) \ge 0$ for all *i*, *a_i*, *a'_i*.



11

• Information structure (S, P): $S = \prod_i S_i$ (finite) and $P = \{P(\cdot|\omega)\}_{\omega \in \Omega}$.

- Information structure (S, P): $S = \prod_i S_i$ (finite) and $P = \{P(\cdot|\omega)\}_{\omega \in \Omega}$.
- p is implemented by (S, P) if there is a (pure) BNE a^* s.t.

$$p(a, \omega) = \mu(\omega)P(\{s: a^*(s) = a\}|\omega) \quad \forall a, \omega.$$

Given (S, P) and μ , let $\mu_i(\omega, s_{-i}|s_i)$ denote *i*'s belief about (ω, s_{-i}) given s_i .

Given (S, P) and μ , let $\mu_i(\omega, s_{-i}|s_i)$ denote *i*'s belief about (ω, s_{-i}) given s_i .

• $i \geq_{lnf}^{s} j$: *i* is weakly more informed than *j* at *s* if

$$\mu_i(\omega, \mathbf{s}_{-i}|\mathbf{s}_i, \mathbf{s}_j) = \mu_i(\omega, \mathbf{s}_{-i}|\mathbf{s}_i)$$

for all $\omega \in \Omega$ and $s_{-i} \in S_{-i}$.

Given (S, P) and μ , let $\mu_i(\omega, s_{-i}|s_i)$ denote *i*'s belief about (ω, s_{-i}) given s_i .

• $i \geq_{lnf}^{s} j$: *i* is weakly more informed than *j* at *s* if

$$\mu_i(\omega, s_{-i}|s_i, s_j) = \mu_i(\omega, s_{-i}|s_i)$$

for all $\omega \in \Omega$ and $s_{-i} \in S_{-i}$.

• $i = {s \atop lnf} j$: *i* and *j* are equally informed at *s* if $i \ge {s \atop lnf} j$ and $j \ge {s \atop lnf} i$.

Horizontal transmission to *i* and *j* at *s* possible if $i = {}^{s}_{lnf} j$.

14

Horizontal transmission to *i* and *j* at *s* possible if $i = {}^{s}_{lnf} j$.

Vertical transmission from *i* to *j* at *s* possible if $i \geq_{lnf}^{s} j$ and *i* satisfies communication incentives.

Horizontal transmission to *i* and *j* at *s* possible if $i =_{lnf}^{s} j$.

Vertical transmission from *i* to *j* at *s* possible if $i \geq_{lnf}^{s} j$ and *i* satisfies communication incentives.

General formalism: Each information structure can be formally categorized according to the extent to which it allows horizontal and vertical transmission.

14

Horizontal transmission to *i* and *j* at *s* possible if $i = s_{lnf} j$.

Vertical transmission from *i* to *j* at *s* possible if $i \geq_{lnf}^{s} j$ and *i* satisfies communication incentives.

General formalism: Each information structure can be formally categorized according to the extent to which it allows horizontal and vertical transmission.

We focus on two limit-case families of organized information structures:

- Single-Meeting Schemes (SMS) illustrating horizontal transmission
- Delegated Hierarchies (DH) illustrating vertical transmission

Characterization:

Single-Meeting Schemes

laurent.mathevet@eui.eu & ina.taneva@ed.ac.uk

In principle (1) the content of a meeting is common knowledge among the participants, (2) who also know the non-participants are less informed. An information structure (S, P) is a single-meeting scheme if there exist a collection $\{M(s) \subseteq \mathcal{I} : s \in S \text{ s.t.} P(s) > 0\}$ and at most one $\tilde{s}_i \in S_i$ for each i such that: (1) $i \in M(s)$ implies $s_i \neq \tilde{s}_i$ and $i \gtrsim^s j$ for all $j \in \mathcal{I}$ and

(2) $i \notin M(s)$ implies $s_i = \tilde{s}_i$.

Information communicated publicly but to a restricted audience: i, j ∈ M(s) ⇒ i =^s_{lnf} j.

- Information communicated publicly but to a restricted audience: i, j ∈ M(s) ⇒ i =^s_{lnf} j.
- Non-participation may carry different information for different players: μ_i(· | s̃_i) ≠ μ_j(· | s̃_j) possible.

18

- Information communicated publicly but to a restricted audience: i, j ∈ M(s) ⇒ i =^s_{lnf} j.
- Non-participation may carry different information for different players: μ_i(· | s̃_i) ≠ μ_j(· | s̃_j) possible.
- Many possible meetings ex-ante: {M(s) ⊆ ℑ: s s.t. P(s) > 0} but only one is ever realized.

Which strategic outcomes can emerge in a game where incomplete information is in the form of single-meeting schemes?

Constrained information design: optimize over a subset of the BCE set.

Theorem 1

A distribution $p \in \Delta(A \times \Omega)$ can be implemented by a SMS if and only if for all $i \in \mathcal{I}$, there is $\tilde{a}_i \in A_i$ such that

$$\sum_{\omega \in \Omega} \sum_{\mathbf{a}_{-i}} p(\tilde{a}_i, \mathbf{a}_{-i}, \omega) \left(u_i(\tilde{a}_i, \mathbf{a}_{-i}; \omega) - u_i(a'_i, \mathbf{a}_{-i}; \omega) \right) \ge 0 \quad \forall a'_i \in A_i,$$

and for all $a_i \in A_i \setminus \{\tilde{a}_i\}$

$$\sum_{\omega\in\Omega} p(a_i, a_{-i}, \omega) \left(u_i(a_i, a_{-i}; \omega) - u_i(a'_i, a_{-i}; \omega) \right) \ge 0 \quad \forall a'_i \in A_i, a_{-i} \in A_{-i}.$$

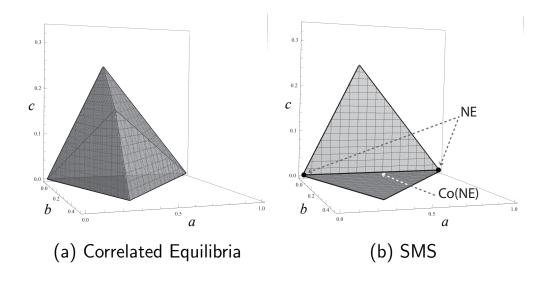
BCE

Example:

	0	1
0	3, 2	0, 0
1	0, 0	2, 3

Battle of the Sexes

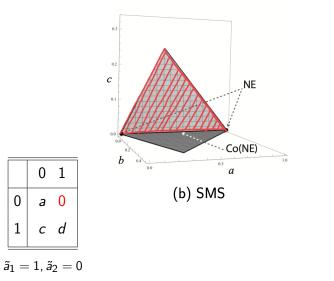
Characterization: SMS in BoS



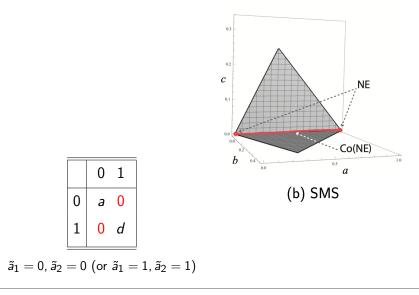
 In coordination games with strict equilibria, SMS(μ) is a union of faces of BCE(μ).

Pure-strategy public information outcomes lie at the intersection of the different classes of SMS (here, the intersection of the faces).

Characterization: SMS in BoS



Characterization: SMS in BoS



Optimality:

Single-Meeting Schemes

Identify environments in which single-meeting schemes and delegated hierarchies are overall optimal?

 \Rightarrow an optimal BCE outcome satisfies the characterizations

Assumption 1 (Binary Actions) For all $i \in \mathcal{I}$, $A_i = \{0, 1\}$.

Assumption 2 (Outside Option) For all $i \in \mathcal{I}$, $u_i = 0$ whenever $a_i = 0$.

Assumption 3 (Complementarities). For all $i \in \mathcal{I}$, $u_i(1, a_{-i}; \omega)$ is weakly increasing in a_{-i} for all $\omega \in \Omega$.

28

Examples :

Linear network

$$u_i(a_i, a_{-i}; \omega) = \gamma_i(\omega) a_i + \sum_{j \neq i} \gamma_{ij}(\omega) a_i a_j$$

 Global games of regime change [Sakovics and Steiner 2012]

$$u_i(1, a_{-i}; \omega) = \begin{cases} b_i - c_i & \text{if } \kappa_i + \sum_{j \neq i} \kappa_j a_j > 1 - \omega \\ -c_i & \text{otherwise.} \end{cases}$$

and $u_i(0, a_{-i}; \omega) = 0.$

Optimality of Single-Meeting Schemes

 $v : A \times \Omega \rightarrow \mathbb{R}$ is increasing (on A) if $a' \ge a \Rightarrow v(a'; \omega) \ge v(a; \omega)$ for all $\omega \in \Omega$.

Optimality of Single-Meeting Schemes

$$v : A \times \Omega \rightarrow \mathbb{R}$$
 is increasing (on A) if
 $a' \ge a \Rightarrow v(a'; \omega) \ge v(a; \omega)$ for all $\omega \in \Omega$.

Let
$$\mathcal{V}^{\mathsf{M}} = \{ \mathbf{v} : \mathbf{A} \times \Omega \to \mathbb{R} : \mathbf{v} \text{ is increasing} \}.$$

30

Optimality of Single-Meeting Schemes

$$v : A \times \Omega \rightarrow \mathbb{R}$$
 is increasing (on A) if
 $a' \ge a \Rightarrow v(a'; \omega) \ge v(a; \omega)$ for all $\omega \in \Omega$.

Let
$$\mathcal{V}^{\mathrm{M}} = \{ \mathbf{v} : \mathbf{A} imes \Omega o \mathbb{R} : \mathbf{v} \text{ is increasing} \}.$$

Theorem 4

If $\{u_i\}$ satisfy Assumptions 1-3 and $v \in \operatorname{cone} (\mathcal{V}^{M} \cup \{u_i\})$, then there is $p^* \in \operatorname{argmax}_{p \in BCE(\mu)} \mathbb{E}_p[v]$ that can be implemented by a singlemeeting scheme.

Thank you!