

# Is it Better to be First? Search with Endogenous Information Acquisition

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Barcelona  
August 2023

# Classical Search Overview

Classical search in Simon (1955), Weitzman (1979):

- DM sequentially samples independent r.v.
- Binary technology for resolving uncertainty
- Fixed cost for item
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DM has **too passive** learning strategy: *sequential interview design*

Endogenous info (RI): flexible learning at cost

*Our* Search & RI:

- DM sequentially samples iid alternatives
- **Flexible learning** about alternative
- **Endogenous, history-dependent** cost for alternative
- DM may learn nothing about alternative, **no recall**

*DM conducts endogenous interviews sequentially*

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- Decreasing threshold: discounting (Salop, 1973)
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**Optimal Interview Design:** is it possible to characterise the optimal search rule?

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**Order Discrimination:** does the order of inspection influences the probability of choice?

- Better to be first: flexible learning (Steiner et al. 2021); search (Armstrong, 2017)
- Mixed evidence: attention discrimination (Bartos et al. 2016); anecdotal evidence (reddit.com)
- *Our results:* depends on **cost function**

- Extremes: no-learning or full learning
- Our DM:
  - obtains **noisy** estimate about quality of candidate
  - controls whole *distribution* of **noise**
  - choice is stochastic



# General Model

- $T$  candidates: iid binary r.v.  $\theta_t = \{0, 1\}$  with  $P(\theta_t = 1) = \mu$
- DM learns at stage  $t$  about candidate  $t$
- Learning
  - posterior distribution  $p_t$ :  $p_t \in \Delta[0, 1]$  :  $\int_{[0,1]} x dp_t(x) = \mu$ .
  - cost for  $p_t$ :  $C(p_t) = k \int_{[0,1]} c(x) dp_t(x)$ .
- DM chooses one candidate without recall
- DM's payoff: expected posterior minus cost of learning

# Reduction to Collection of Static Problems

- no recall  $\Rightarrow$
- no state variable in dynamic problem  $\Rightarrow$
- in period  $t$  after learning two actions available: *choose candidate* / *continue search* with **exogenous** outside option  $V_{T-t} \Rightarrow$
- collection of static problems with different outside options

# Difficulty and Optimality

## Definition 1

Interview  $(x^L, x^H)$  is *more difficult* than  $(y^L, y^H)$  if

$$x^L > y^L, x^H > y^H$$

Optimality of interviews with *decreasing difficulties* as feature of **flexible** learning

# Satisficing with Endogenous Information

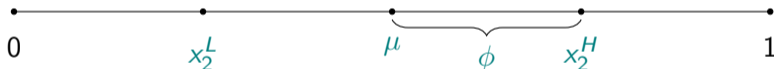
- Restricted Model:
  - $\mu = 0.5$
  - Function  $c(x)$  is symmetric around  $\mu$ ,  $c(\mu) = 0$
  - Only symmetric posteriors available:  $x_t^H - \mu = \mu - x_t^L$

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- Learning Strategy:

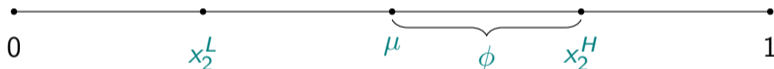


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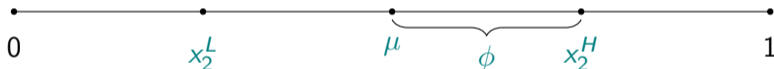
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- Expected payoff:

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- Optimal  $\phi$  is independent from  $T$ : satisficing threshold

## Harder Test is Better

- Fix symmetric posteriors and increase both by  $\delta$ :  $\Delta x_t^H = \Delta x_t^L = \delta$
- Probabilities and rewards change:  $p_t^H \downarrow$ ,  $x_t^H \uparrow$ ,  $p_t^L \uparrow$



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- First-order effect of reward:

$$\begin{aligned} p_t^H \Delta x_t^H + \Delta p_t^H V_{T-t} - \Delta p_t^H x_t^H &= [\text{Symmetry, } \mu = 0.5] \\ &= \Delta p_t^H (V_{T-t} - 0.5) > 0 \end{aligned}$$

It is better to increase both posteriors!

# Main Theorem

## Theorem 1

Let  $c(x)$  be convex, twice differentiable then

$x_t^L, x_t^H$  are decreasing in  $t$

Moreover,

$$\lim_{t \rightarrow \infty} x_t^L = \mu, \quad \lim_{t \rightarrow \infty} x_t^H = x'$$

# Optimal Posteriors

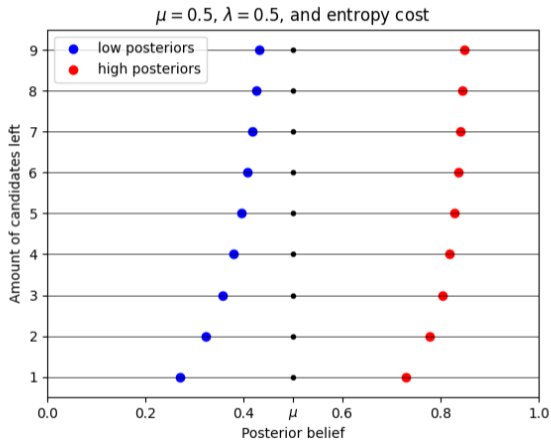


Figure: Optimal posterior beliefs given the amount of candidates left

# Properties of Optimal Learning

- ①  $x_t^H$  dynamics: cherry-picking
- ②  $x_t^L$  dynamics: *rational* procrastination, postponing info acquisition
- ③  $x_t^H$  &  $x_t^L$  dynamics: interview  $t$  is *more difficult* than interview  $t - 1$

# Better to be First?

**better to be first**

hired if success

**better to be last**

the easiest interview

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Proposition 1

Let  $c(x) = k(x - \mu)^2$  then

unconditional probabilities of choice  $P_t$  are *decreasing* in  $t$

It is better to be first!

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- $T = 2$
- $c(x)$  is symmetric around point  $y$ , smooth enough

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## Proposition 2

If  $c'(x)$  is concave on  $(0, y)$  and  $c'(x)$  is convex on  $(y, 1)$  then exists  $y', y''$  such that

if  $\mu \in (y'', y)$  then  $P_2 > P_1$ ;

if  $\mu \in (y, y')$  then  $P_1 > P_2$

- Condition for  $c'(x)$  holds for entropy cost:  
if  $\mu > 0.5$  DM chooses **first** more often, if  $\mu < 0.5$  DM chooses **second** more often



# Beyond $T = 2$ case

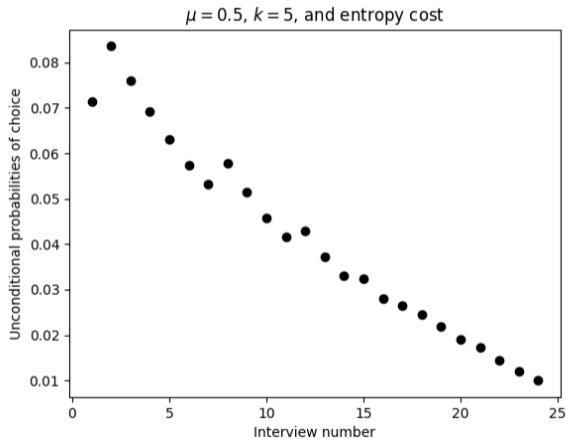


Figure: Non-monotone unconditional probabilities

Optimal search rule: DM *decreases* difficulty of interviews

- 1 Cherry-picking
- 2 Postponing info acquisition

Discrimination: depends of cost function properties

- 1 if  $c'''(x) = 0$  better to be first
- 2 if  $c'''(x) \neq 0$  and  $T = 2$  attention discrimination