#### A Continuous Time Experiment on Linking Formation

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- Theory
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  - strategies and computations are complex
  - multiple equilibria in many models
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• Goal: test these predictions.

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- Individuals choose to form links.
- Linking gives access to other individuals' values: the values of neighbours, and of neighbours' neighbours...
- Maintaining connections is costly.
- The value flow can be either one-way or two-way.
  - one-way: the link that agent *i* forms with agent *j* yields benefits solely to agent *i*.

• two-way: the benefits accrue to both agents.

- $N = \{1, 2, ..., n\}$  with  $n \ge 3$
- Each player  $i \in N$  chooses a set of links  $g_i$  with others,  $g_i = (g_{i1}, \ldots, g_{ii-1}, g_{ii+1}, \ldots, g_{in})$ , and  $g_{ij} \in \{0, 1\}$  for any  $j \in N \setminus \{i\}$ .
- Thus links are unilateral in this game.
- A strategy profile  $g = (g_1, g_2, .., g_n)$  specifies the links made by every player and induces a directed graph, g.

- one-way model:  $\Pi_i(g) = V + \sum_{j \in C_i(g)} \delta^{d(i,j;g)} V \eta_i(g) k$
- two-way model:  $\Pi_i(g) = V + \sum_{j \in C_i(ar{g})} \delta^{d(i,j;ar{g})} V \eta_i(g) k$ 
  - V represents the value of benefit from a connection.
  - $C_i(g)$  is the set of agents that *i* is path-connected to.
  - $\delta \in (0,1]$  is the decay factor of value
  - $\bar{g}$  is the closure of g:  $\bar{g}_{ij} = \max(g_{ij}, g_{ji})$  for every  $i, j \in N$ .
  - d(i, j; g) is the length of the shortest path between i and j.
  - $\eta_i(g) = |\{j \in N : g_{ij} = 1\}|$  is the number of links *i* formed.

• k is the cost of a link.

- value of an agent: V = 10
- four treatments:
  - two-way, n = 10 ( $\delta = 0.9$ , k = 20)
  - two-way,  $n = 50~(\delta = 0.9,~k = 100)$
  - one-way,  $n = 10 \ (\delta = 1, \ k = 20)$
  - one-way,  $n = 50 \ (\delta = 1, \ k = 100)$
- $\delta$ : decay factor of value; k: cost per link

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•  $\frac{k}{n}$  kept constant across treatments

### Efficient and Nash networks

For both n = 10 and n = 50:

- one-way: cycle network
- two-way: star network









#### • Individuals face a complex decision.

- compare costs and benefits of linking
- challenging to compute the value of a link

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  - large evolving network
- very unclear what sorts of networks will actually emerge
- How does bounded rational decision-making at an individual level generate aggregate outcomes?

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- existing work: small groups (4-8)
- A: simultaneous choice
  - Goeree et al. (2009): reject the two-way prediction
  - Falk and Kosfeld (2012): match in one-way but reject two-way model
  - Caria and Fafchamps (2020); Callander and Plott (2005): reject the one-way prediction

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- B: asynchronous choice:
  - Berninghaus et al. (2006): match prediction in two-way
  - Friedman and Oprea (2012): continuous time leads to high cooperation rate in repeated prisoner's dilemma game.

- unclear if these findings scale with size
- novelty of our work:
  - large and small groups
  - asynchronous decision in continuous time

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• one-way and two-way flow

- continuous time and asynchronuous decision
- 6 minutes a round
- At any instant in the 6-minute game, a subject can form/delete a link with any other subject.
- At any moment, each subject is informed about the network structure and about their own payoff.

- The first minute is a trial period and a time moment is randomly chosen from the last 5 minutes for payment.
- 4 groups per treatment and 6 rounds per group

#### Experimental results — snapshots



(c) 
$$N = 50$$
 (one-way): minute 6

(d) N = 50 (two-way): minute 6

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Social efficiency



## Size of the largest component (normalised)

- two-way: fract. in largest component of undirected network
- one-way: fract. in largest (strongly connected) component of directed network



## Summary: aggregate statistics

	one-way	one-way	two-way	two-way
	(n = 10)	(n = 50)	(n = 10)	(n = 50)
social officionay	77.2%	37.6%	82.8%	71.9%
social enciency	(100%)	(100%)	(100%)	(100%)
average distance	3.59	6.13	2.11	2.81
	(5)	(25)	(1.8)	(1.98)
med/max degree	0.578	0.145	0.086	0.031
	(1)	(1)	(0.11)	(0.02)
% largest comp.	80.2%	52.8%	93.2%	96.8%
	(100%)	(100%)	(100%)	(100%)
mean outdegree	1.10	1.28	0.93	1.31
	(1)	(1)	(0.9)	(0.98)

equilibrium prediction in parenthesis.

- How do subjects do so well in the two way model?
- Why is there a breakdown of connectedness and efficiency loss in the one-way model (especially for *n* = 50)?

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	one-way	one-way	two-way	two-way
	(n = 10)	(n = 50)	(n = 10)	(n = 50)
active rate (AR)	9.46%	8.61%	10.3%	9.90%
AR given max pay $\leq 0$	3.57%	3.37%	4.91%	4.60%
AR given <b>max pay &gt; 0</b>	27.4%	16.1%	20.9%	16.2%
best response rate (BRR)	76.0%	59.4%	66.2%	54.7%
BRR given active	36.6%	28.1%	31.6%	29.0%

Individual-level performance in one-way is no worse than that in two-way

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### Noisy myopic best response simulations

- For  $t \leq 60$ , each player randomly makes action
- For t > 60, myopic best response with probability  $1 \epsilon$ , random with probability  $\epsilon$

Figure: Efficiency for different error rate  $\epsilon$ 



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#### Figure: Efficiency for different error rate $\epsilon$



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- one-way model is sensitive to decision noises
- two-way model is robust to decision noises
- more difficult to achieve high social efficiency and be close to theoretical prediction in the one-way model than in the two-way model

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- Theory predicts radically different structures in the two models.
- conducted continuous time network formation experiment
  - small groups close to predictions: different from existing research
  - large groups breakdown of connectedness and efficiency in the one way model, high efficiency and connectedness in the two way model

• Small noises in decision create great disruption in the one-way model.

# Thank you!

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